

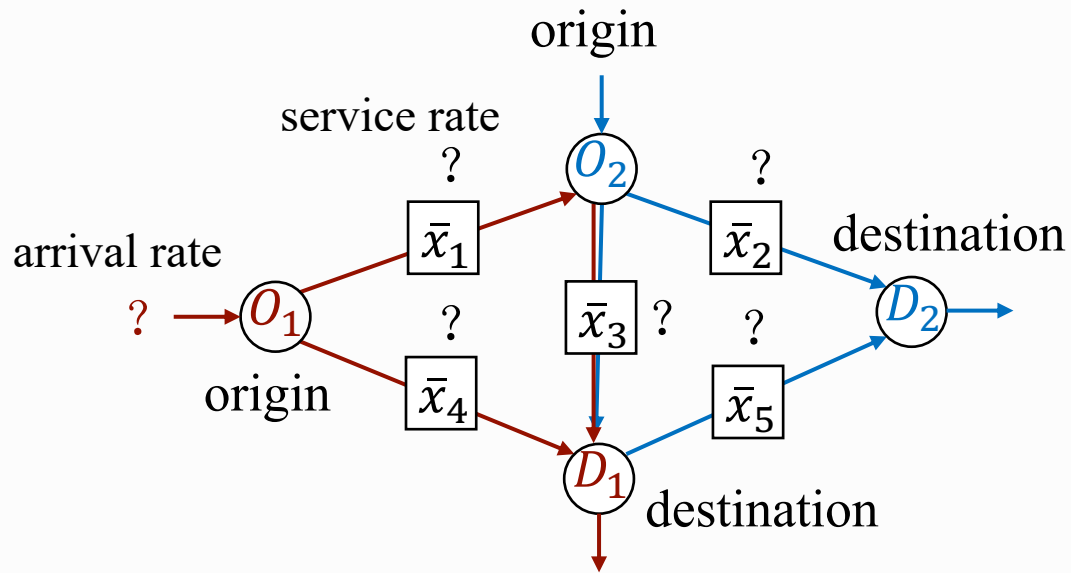
Data-Efficient Decision-making under Uncertainty: AutoML and Beyond

Qian Xie 谢倩 (Cornell)

Job talk for engineering school audiences

Research Overview: Decision-making under Uncertainty

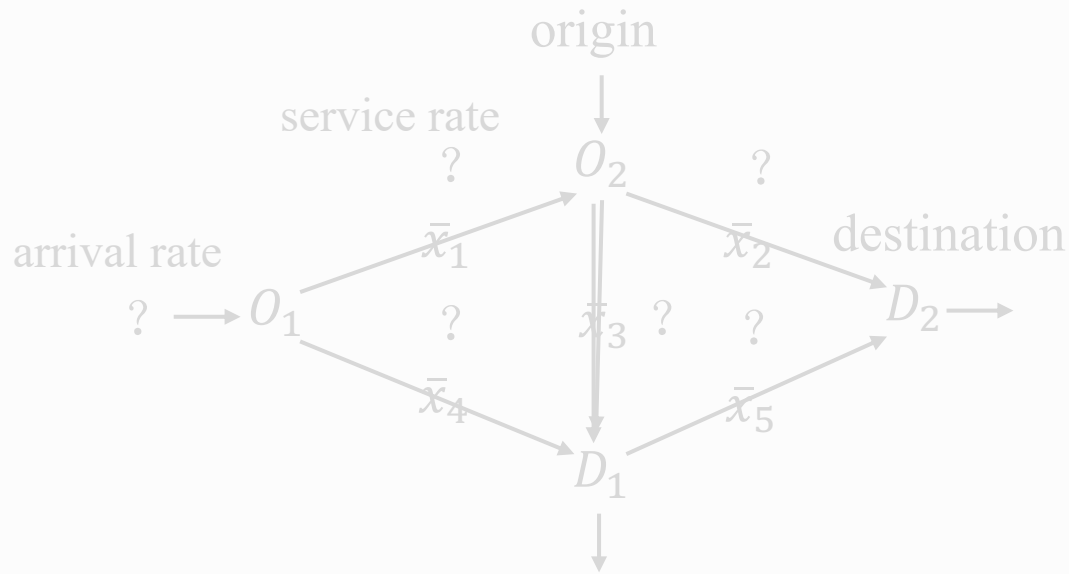
- Earlier: stochastic control (actions chosen to regulate system)
- **Unknown** system rates (robust/model-free control) [IEEE TCNS]



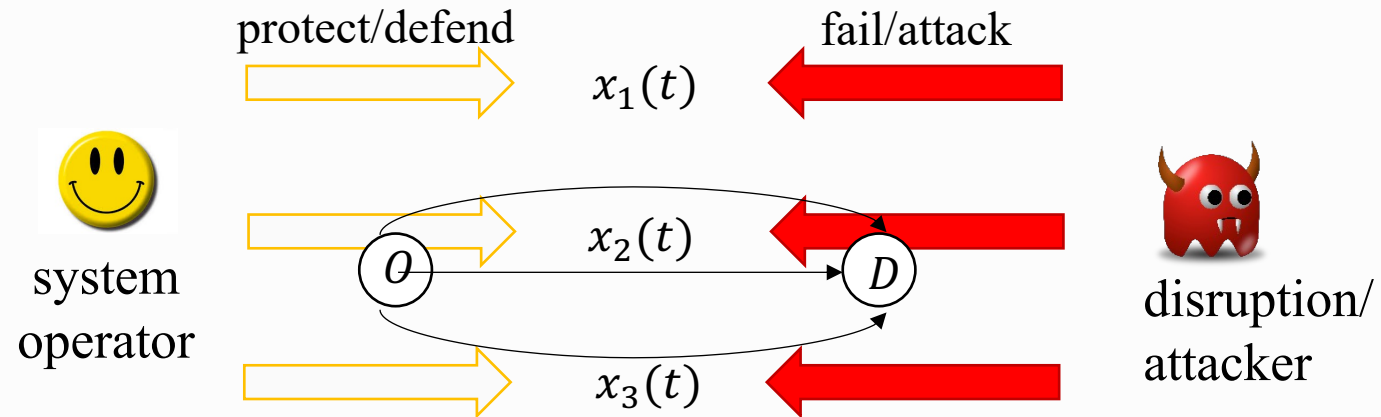
“Stabilizing Queueing Networks with Model Data-Independent Control.” IEEE TCNS.

Research Overview: Decision-making under Uncertainty

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 - **Random** failure/attack realizations (optimal & robust control) [Automatica]



“Stabilizing Queuing Networks with Model Data-Independent Control.” IEEE TCNS.



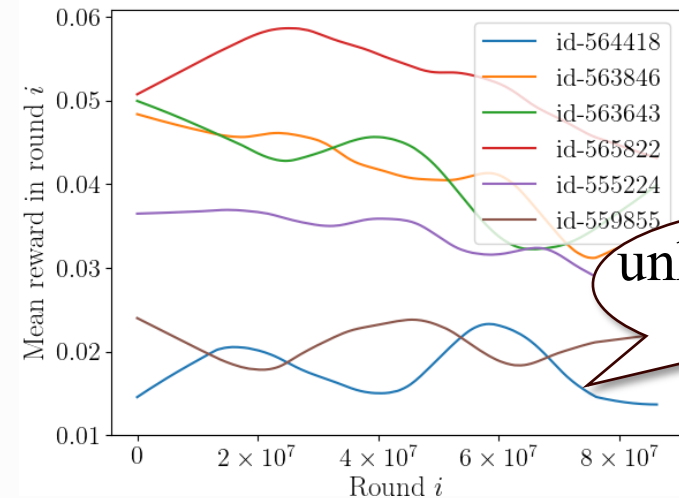
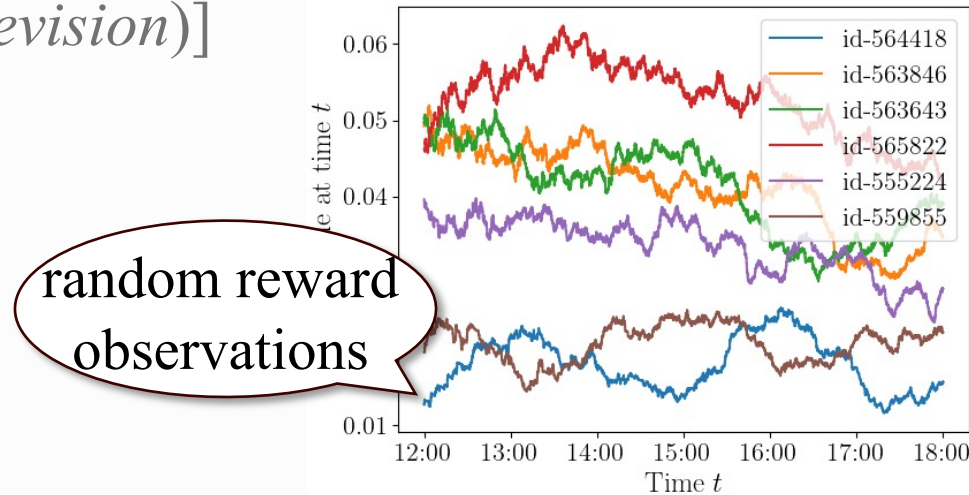
“Cost-aware Defense for Parallel Server Systems against Reliability and Security Failures.” Automatica.

Research Overview: Decision-making under Uncertainty

- Earlier: stochastic control (actions chosen to regulate system)
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- **Recent: learning-based decision-making** (actions chosen to reduce uncertainty due to limited feedback)





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 - **Unknown** reward function; **random** observations (bandits) [ICML'23 + OR (*major revision*)]



“Smooth Nonstationary Bandits.” ICML’23

Research Overview: Decision-making under Uncertainty

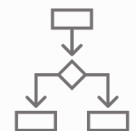
- **Recent: learning-based decision-making** (actions chosen to reduce uncertainty due to limited feedback)
 - Unknown reward function; random observations (bandits) [ICML'23 + *OR*]
 - **Unknown** objective functions (**black-box** optimization) with
 -  varying evaluation costs [NeurIPS'24 + INFORMS DM Paper Finalist]
 -  adaptive stopping time [Under review + AutoML'25 (non-archival)]
 -  multi-stage feedback [To be submitted]
 -  multi-source environment information [NeurIPS'25 LAW]



"Cost-aware Bayesian Optimization via the Pandora's Box Gittins Index." NeurIPS'24.



"Cost-aware Stopping for Bayesian Optimization." Under review.



"Bayesian-optimal Decision-making under Cost-aware Multi-stage Feedback via the Gittins Index."



"LLM-Driven Composite NAS for Multi-Source RL State Encoding." NeurIPS'25 LAW.

Research Overview: Decision-making under Uncertainty

- Recent: learning-based decision-making (actions chosen to reduce uncertainty due to limited feedback)

- Unknown reward function; random observations (bandits) [ICML'23 + QR]

- Unknown objective functions (black-box optimization) with **This talk's focus**

 varying evaluation costs [NeurIPS'24 + INFORMS DM Paper Finalist]

 adaptive stopping time [Under review + AutoML'25 (non-archival)]


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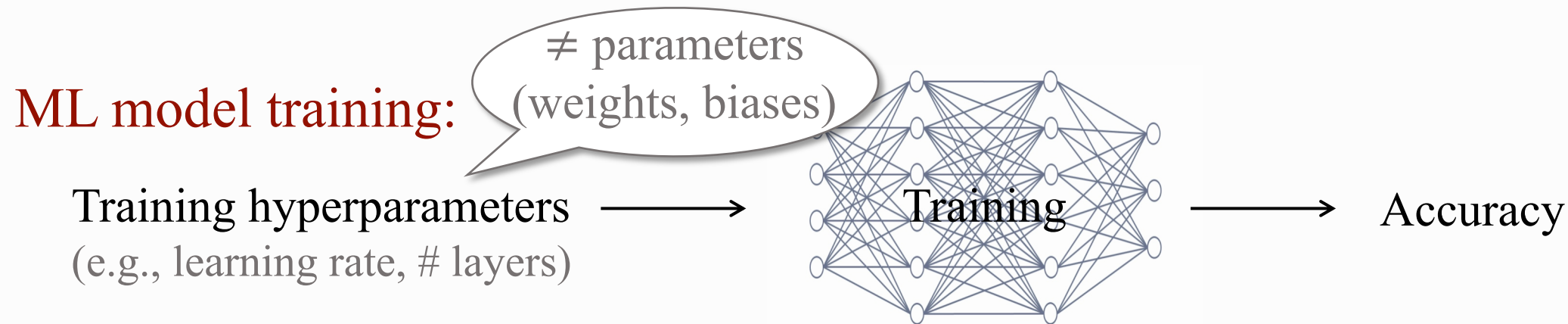
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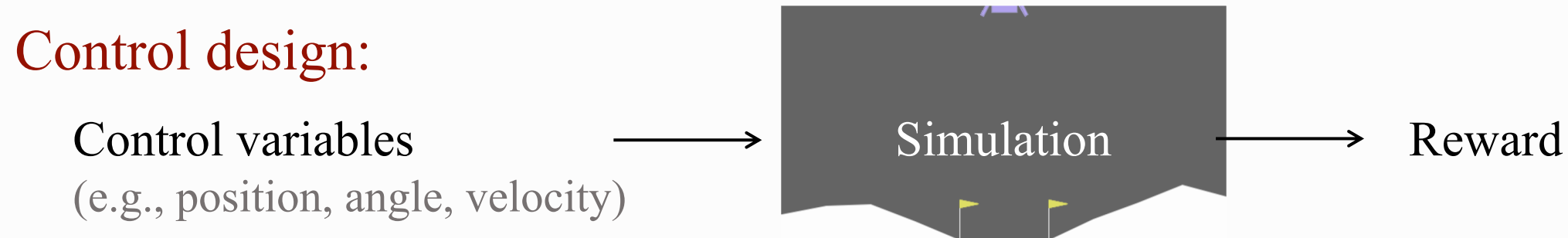
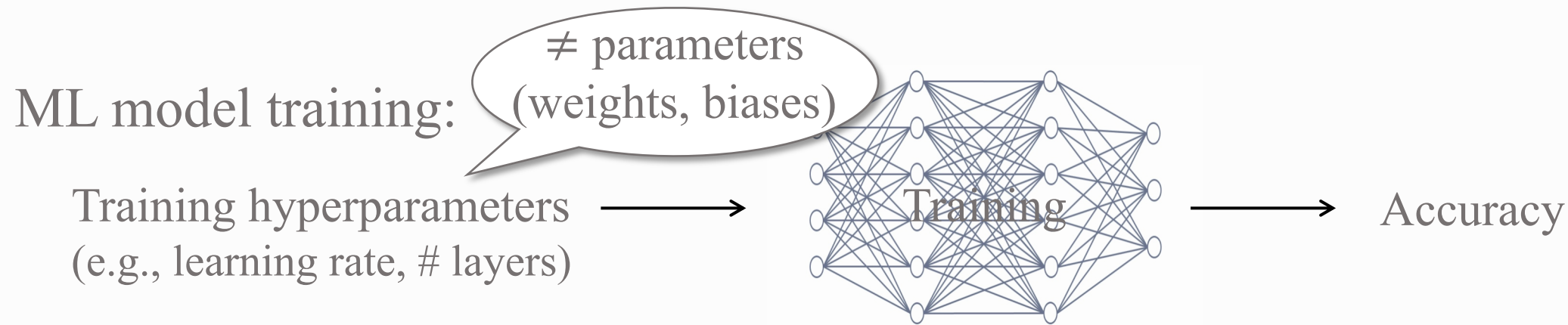
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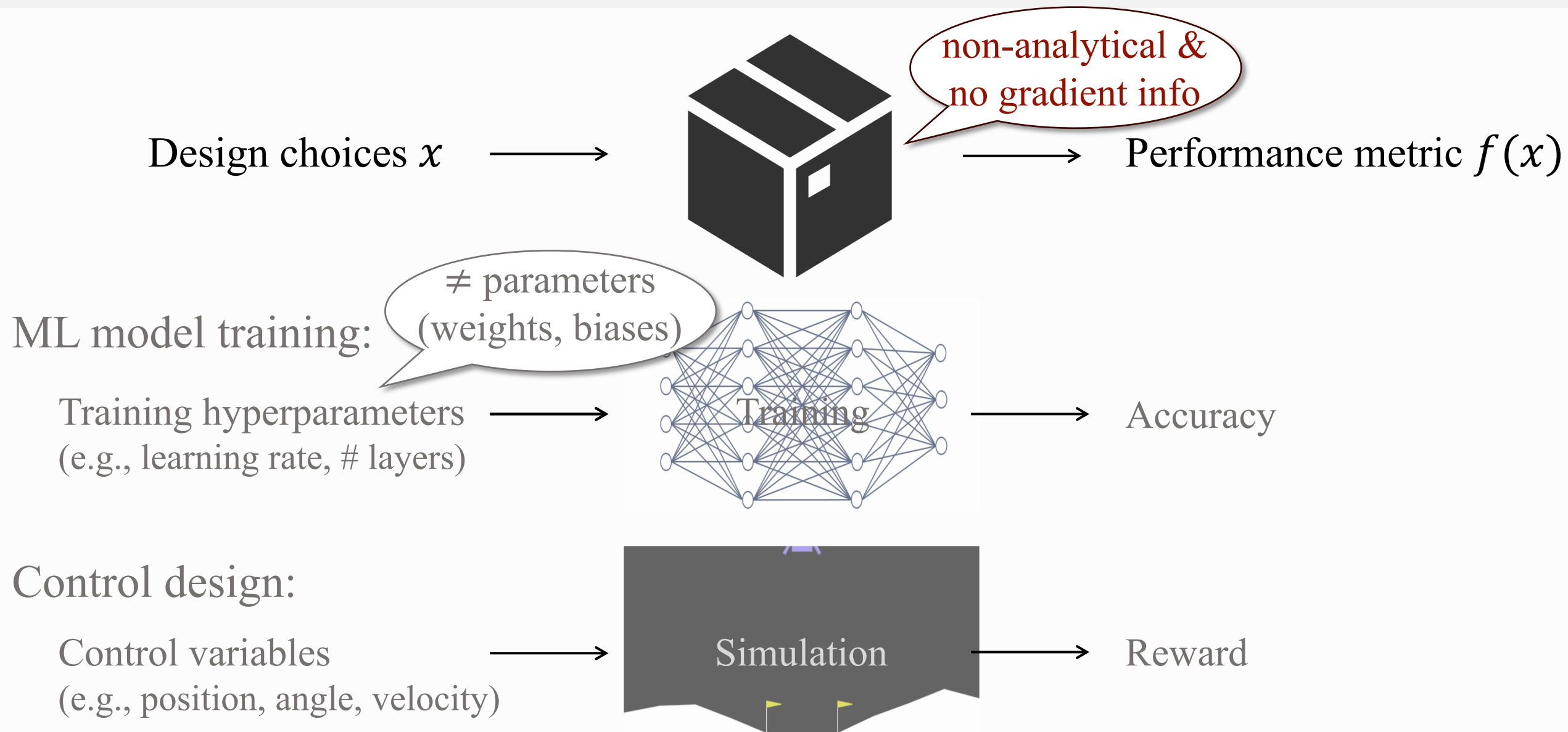
Motivation: World of Optimization under Uncertainty



Motivation: World of Optimization under Uncertainty



Motivation: World of Optimization under Uncertainty



Motivation: World of Optimization under Uncertainty

Black-box optimization:

(gradient-based methods not applicable)

Input x →



non-analytical &
no gradient info

→ Observed outcome $f(x)$

ML model training:

≠ parameters
(weights, biases)

Training hyperparameters
(e.g., learning rate, # layers) →



→ Accuracy

Background: Black-Box Optimization

Black-box optimization:
(gradient-based methods not applicable)

Input x →

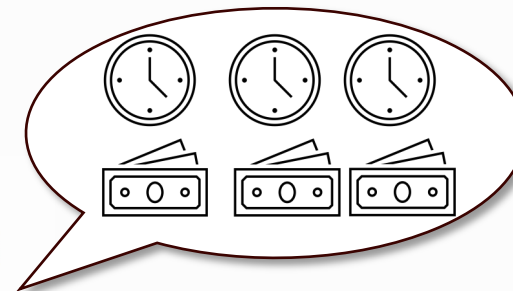


expensive-to-evaluate

→ Observed outcome $f(x)$

ML model training:

Training hyperparameters
(e.g., learning rate, # layers) →



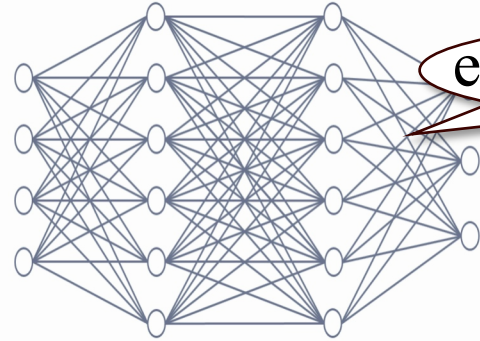
Training time
Compute credits

→ Accuracy

Naïve (Non-Adaptive) Approach: Grid Search

ML model training:

Training hyperparameters



expensive-to-evaluate



Accuracy

| Training hyperparameter | Range | Number of Options |
|-------------------------|--------------|-------------------|
| Batch size | [16, 512] | 10 |
| Learning rate | [1e-4, 1e-1] | 10 |
| Momentum | [0.1, 0.99] | 10 |
| Weight decay | [1e-5, 1e-1] | 10 |
| Number of layers | {1, 2, 3, 4} | 4 |
| Max units per layer | [64, 1024] | 10 |
| Dropout | [0.0, 1.0] | 10 |

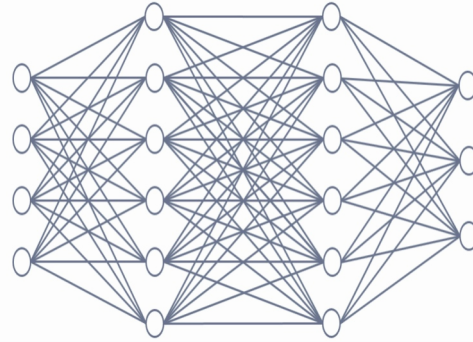
40,000,000
combinations!

Data-Driven (Adaptive) Approach

Automated machine learning:
(AutoML)



Hyperparameters
(e.g., learning rates)

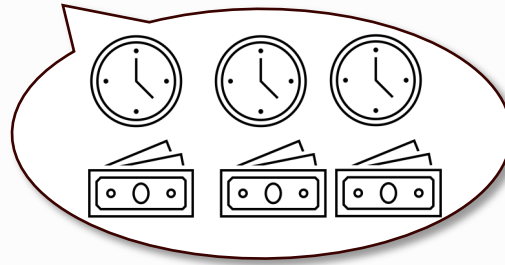


Training Pipeline



Performance metric
(e.g., accuracy)

Run next evaluation



Provide feedback



Data-efficient decision rule
(What to try next, when to stop)

Existing Umbrellas of Black-Box Optimization

Naïve (non-adaptive) approaches:

- Grid search
- Random search
- Manual tuning

Data-driven (adaptive) approaches:

- Local search (e.g., simulated annealing)
- Evolutionary algorithms (e.g., genetic algo)
- Bayesian optimization (e.g., EI, UCB, TS)
- Reinforcement learning (e.g., PPO, ENAS)
- LLM-based search agent (e.g., GENIUS)

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Limitations in practice:

1. Limited principled guidance (e.g., naïve)
2. Often data-inefficient (e.g., naïve, local search, evolutionary algo)
3. No or ad-hoc incorporation of additional side info (most)
(e.g., varying training time across search space)

Overview of Contributions Across My Work

| Naïve (non-adaptive) approaches: | Data-driven (adaptive) approaches: |
|----------------------------------|--|
| • Grid search | • Local search |
| • Random search | • Evolutionary algorithms |
| • Manual tuning | • Bayesian optimization ★  Part I |
| | • Reinforcement learning ★  Part II |
| | • LLM-based search agent ★ |

Contributions of methods in my work:

1. Principled guidance
2. Competitive empirical performance
3. Principled incorporation of additional side info

★ New methods under this umbrella

Outline

Part I (Recent):

Bayesian Optimization via Gittins Index Design Principle

Part II (Ongoing):

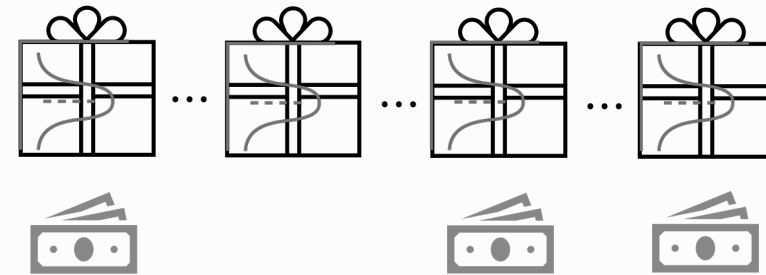
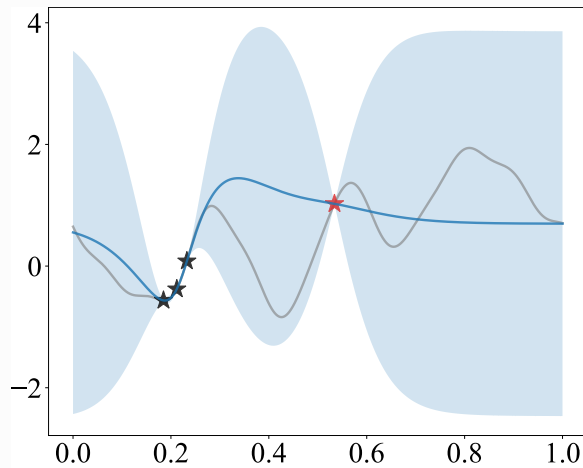
Black-box Optimization Beyond AutoML

Reinforcement Learning · Engineering Design · Scientific Discovery · LLM

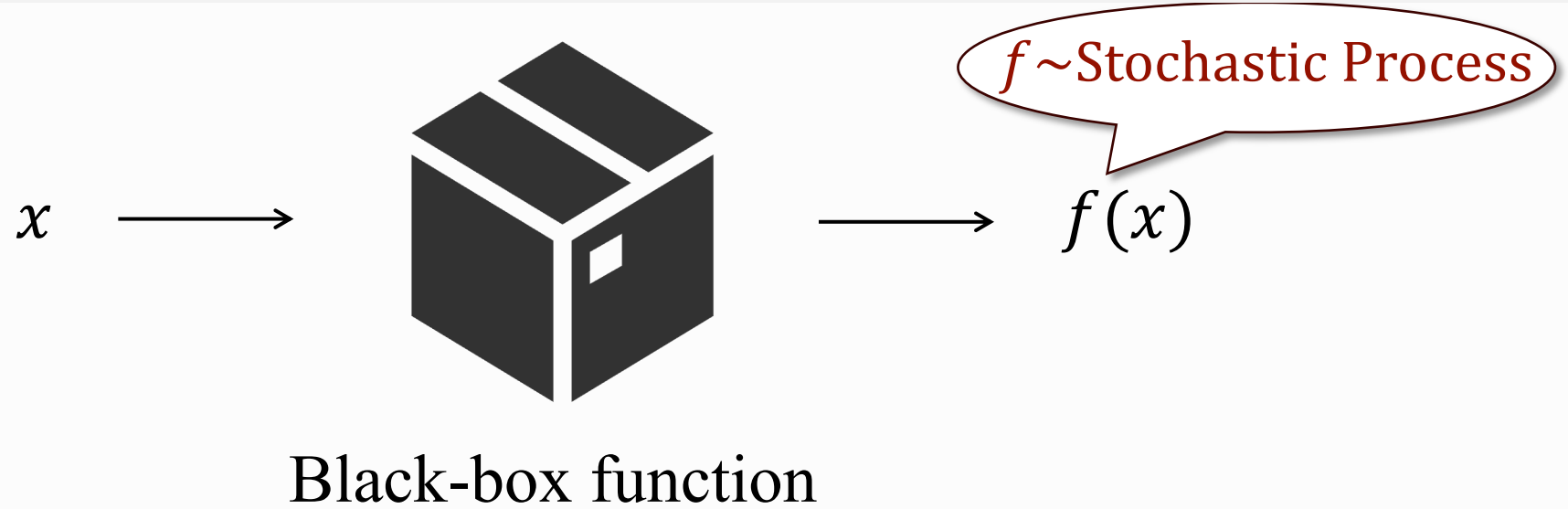
Part I (Recent):

Bayesian Optimization via Gittins Index

Design Principle

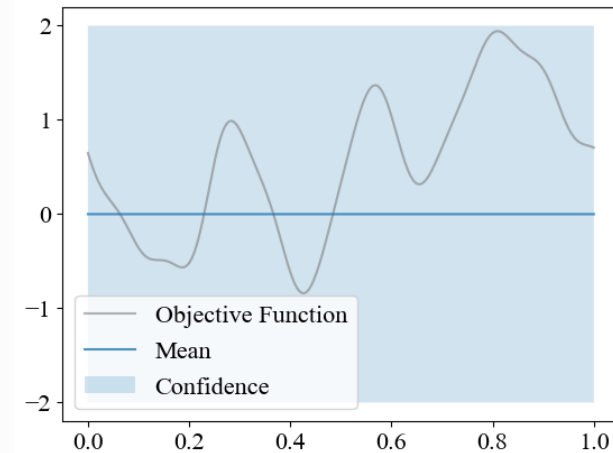
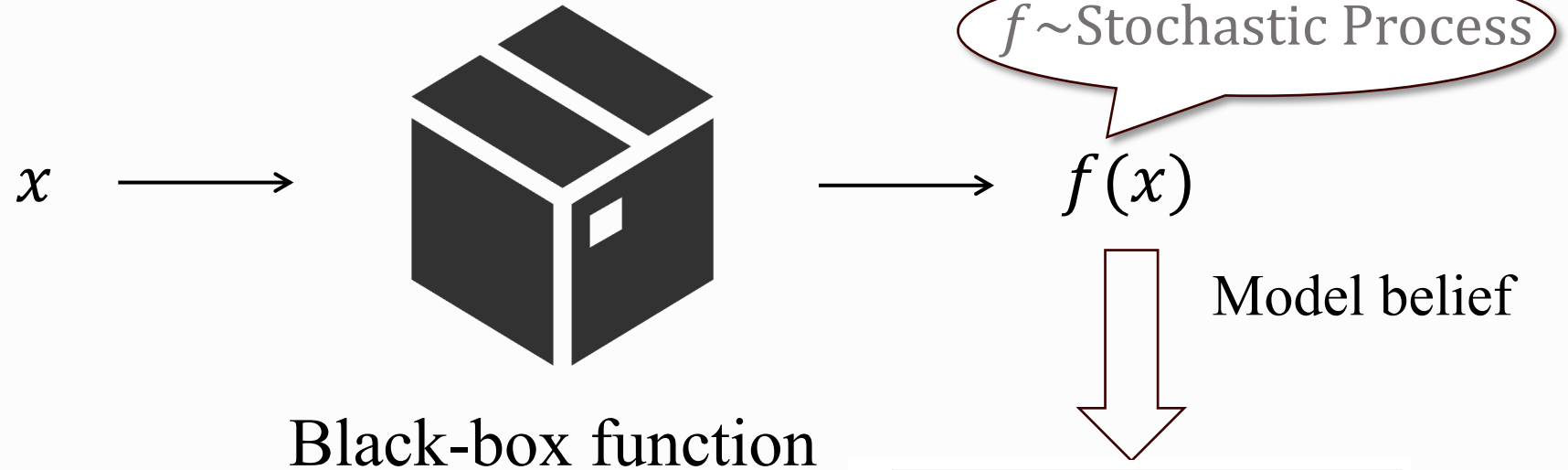


Bayesian Optimization



Bayesian Optimization

Time 0

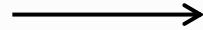


Probabilistic model
(e.g., Gaussian process)

Bayesian Optimization

Time t

x_1, \dots, x_t



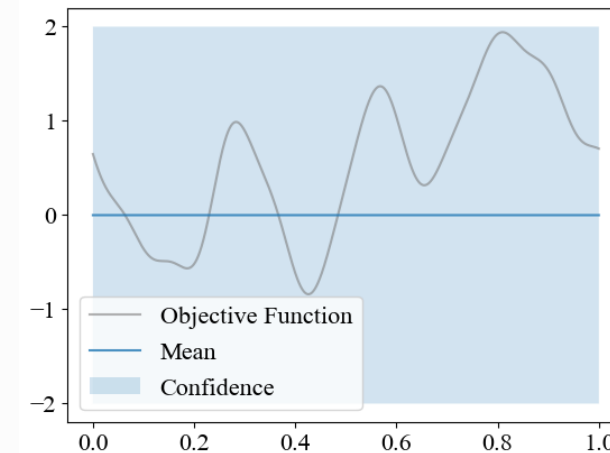
Black-box function



$f \sim \text{Stochastic Process}$

$f(x_1), \dots, f(x_t)$

Model belief



Probabilistic model
(e.g., Gaussian process)

Bayesian Optimization

Time t

x_1, \dots, x_t

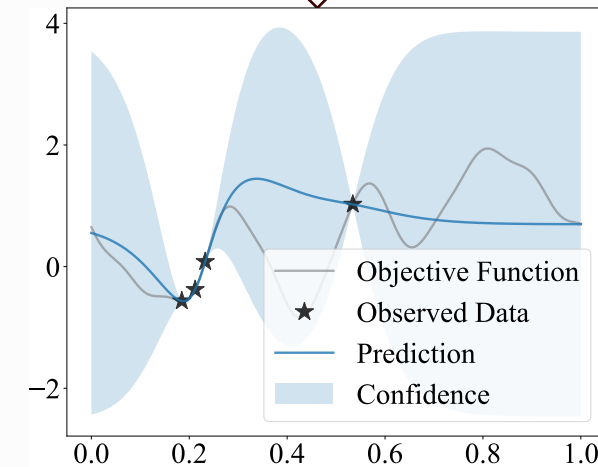


Black-box function

$f \sim \text{Stochastic Process}$

$f(x_1), \dots, f(x_t)$

Update belief
(Bayes' rule)

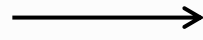


Probabilistic model
(e.g., Gaussian process)

Bayesian Optimization

Time t

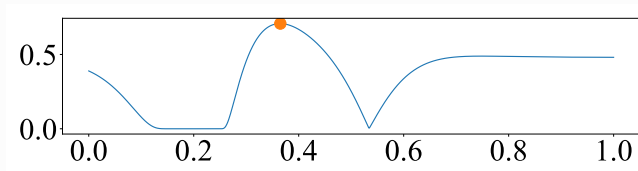
x_1, \dots, x_t



$f(x_1), \dots, f(x_t)$

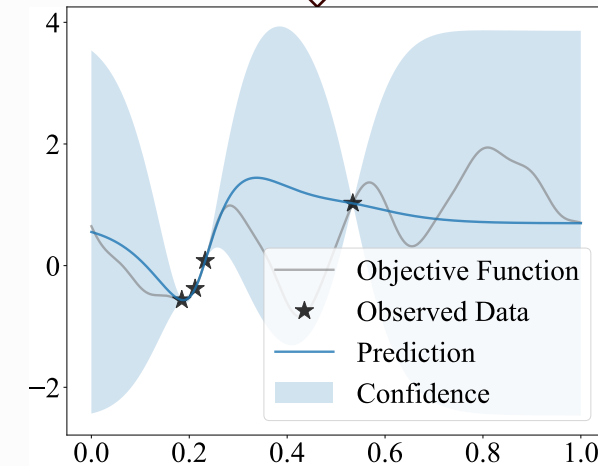
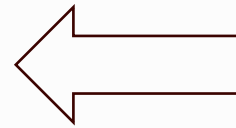
Black-box function

Update belief
(Bayes' rule)



Decision rule
(e.g., EI, UCB, TS)

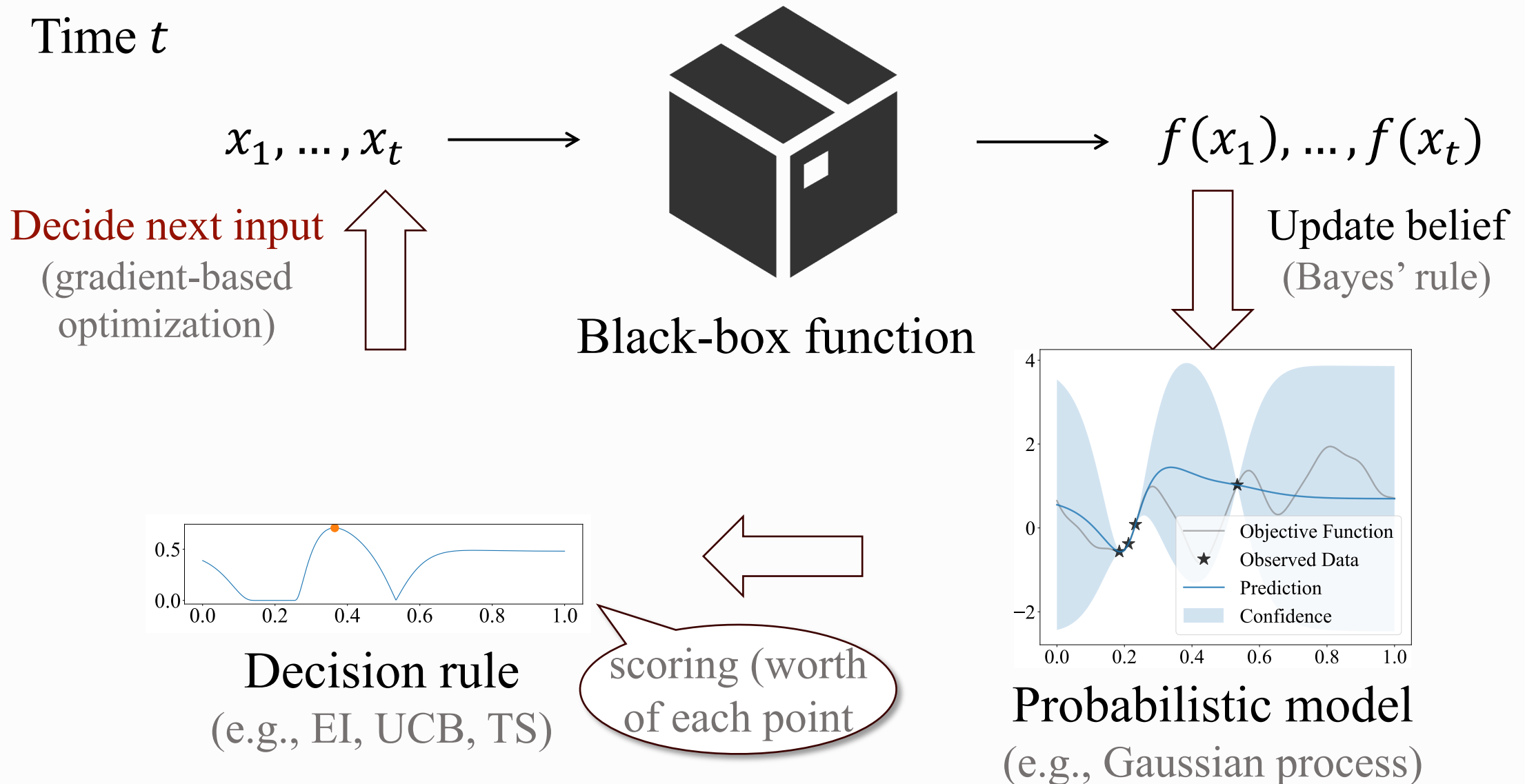
scoring (worth
of each point)



Probabilistic model
(e.g., Gaussian process)

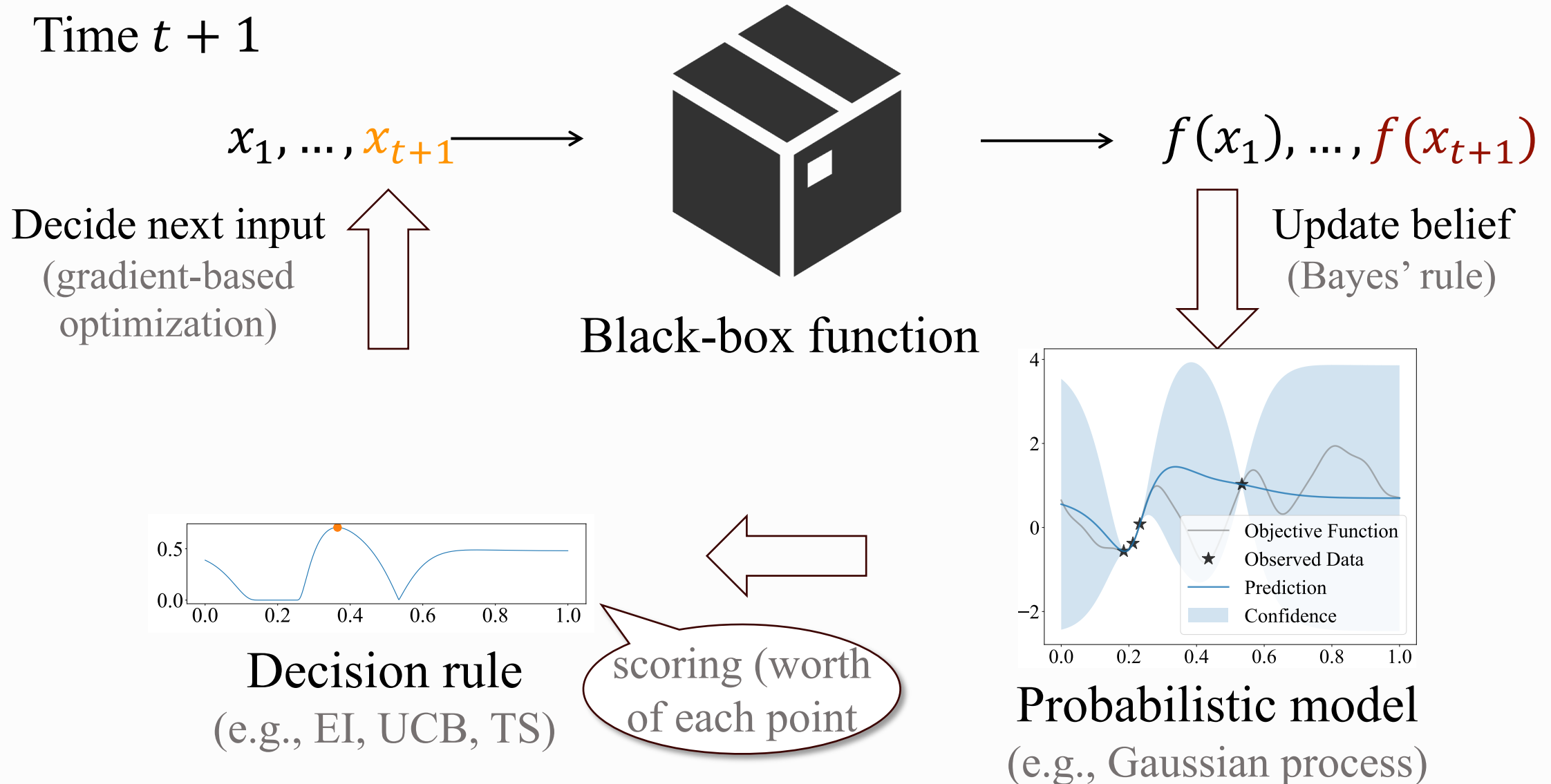
Bayesian Optimization

Time t



Bayesian Optimization

Time $t + 1$



Bayesian Optimization

Time $t + 1$

x_1, \dots, x_{t+1}



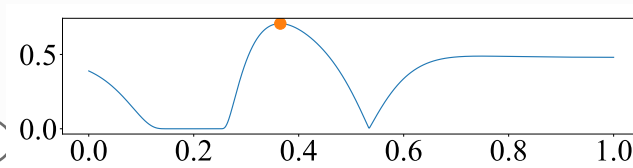
$f(x_1), \dots, f(x_{t+1})$

Decide next input
(gradient-based
optimization)



Black-box function

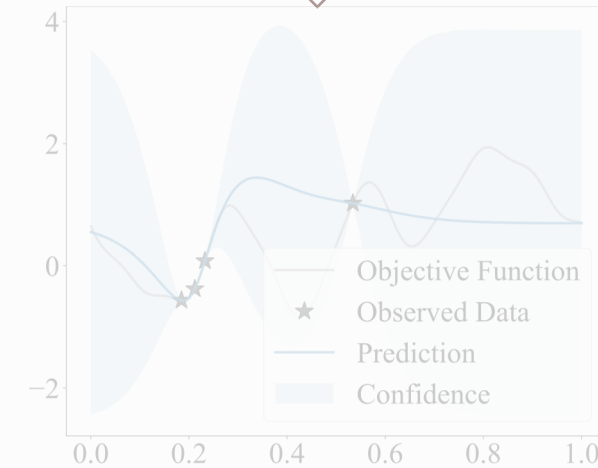
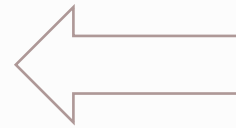
Update belief
(Bayes' rule)



My focus

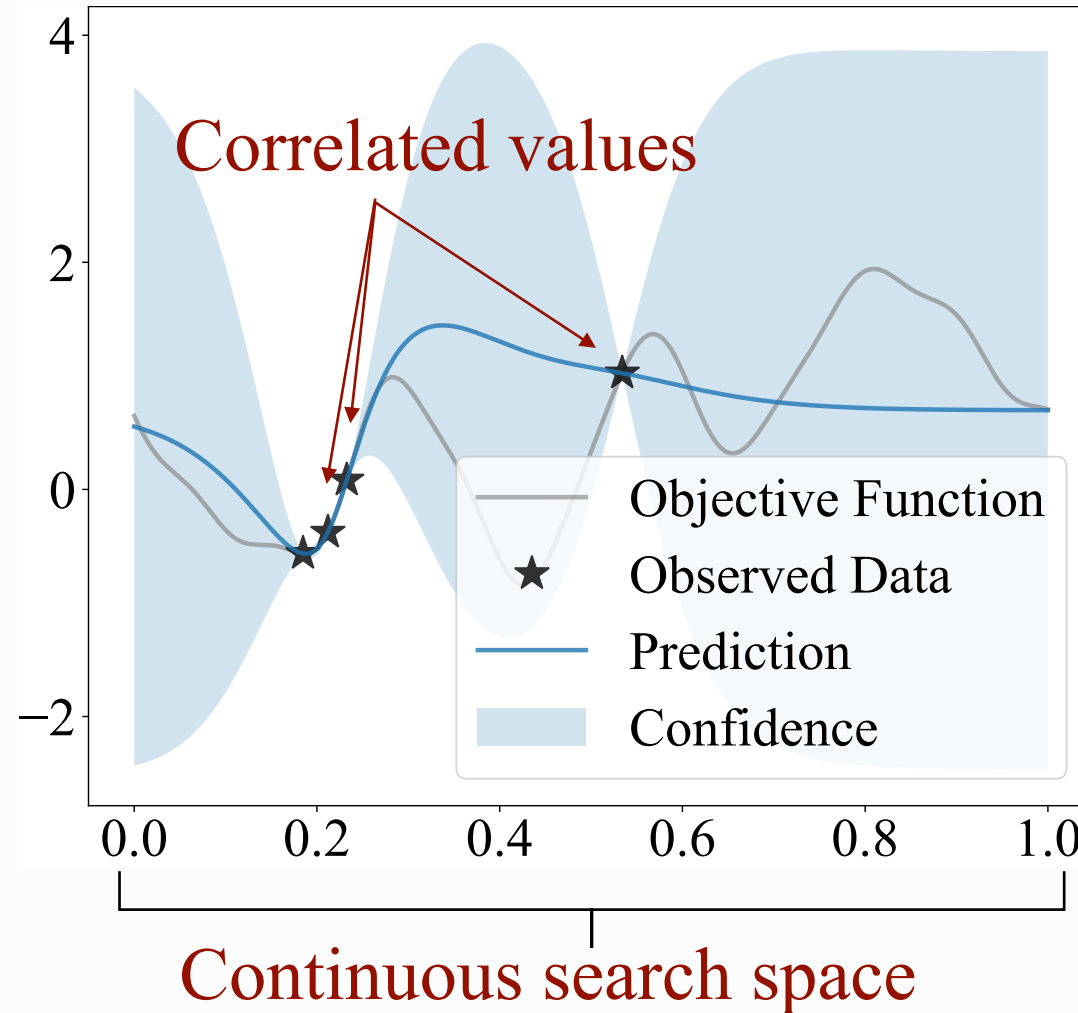
Decision rule
(e.g., EI, UCB, TS)

scoring (worth
of each point)



Probabilistic model
(e.g., Gaussian process)

Challenges in Decision Rule Design



Correlation & continuity \Rightarrow Intractable MDP \Rightarrow Optimal policy unknown

Popular Decision Rule: Expected Improvement

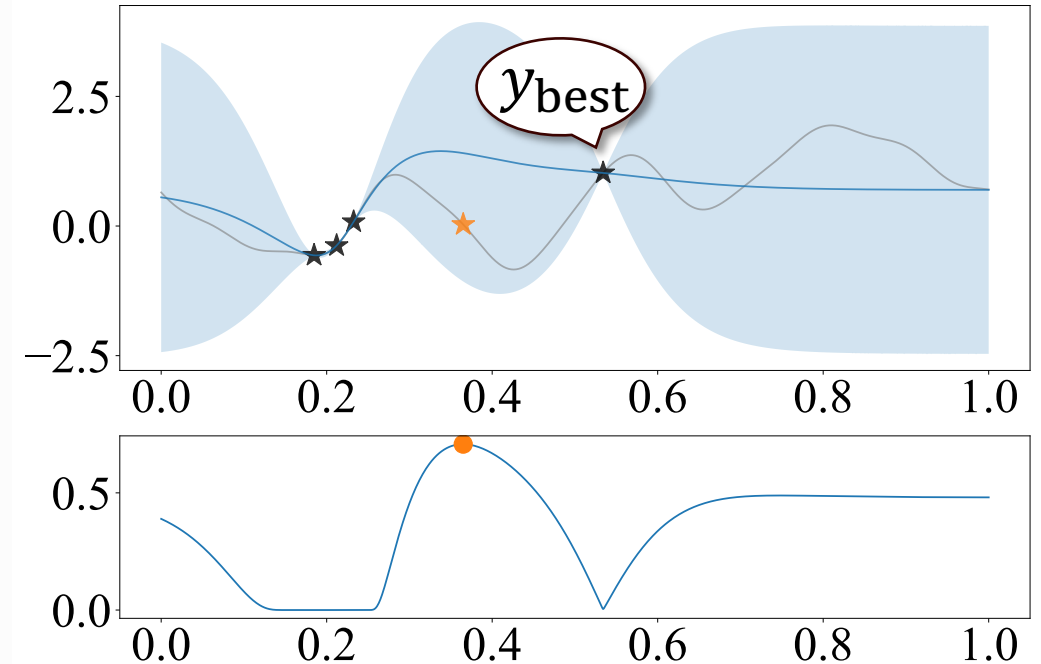
$$\text{EI}(x) = \mathbb{E}[\underbrace{\max(f(x) - y_{\text{best}}, 0)}_{\text{"improvement"}} \mid x_1, \dots, x_t]$$

current best observed y_{best} data D

$$x_{t+1} = \max_x \text{EI}_{f|D}(x)$$

posterior distribution

One-step approximation to MDP



Expected improvement $\text{EI}(x)$

Popular Decision Rule: Expected Improvement

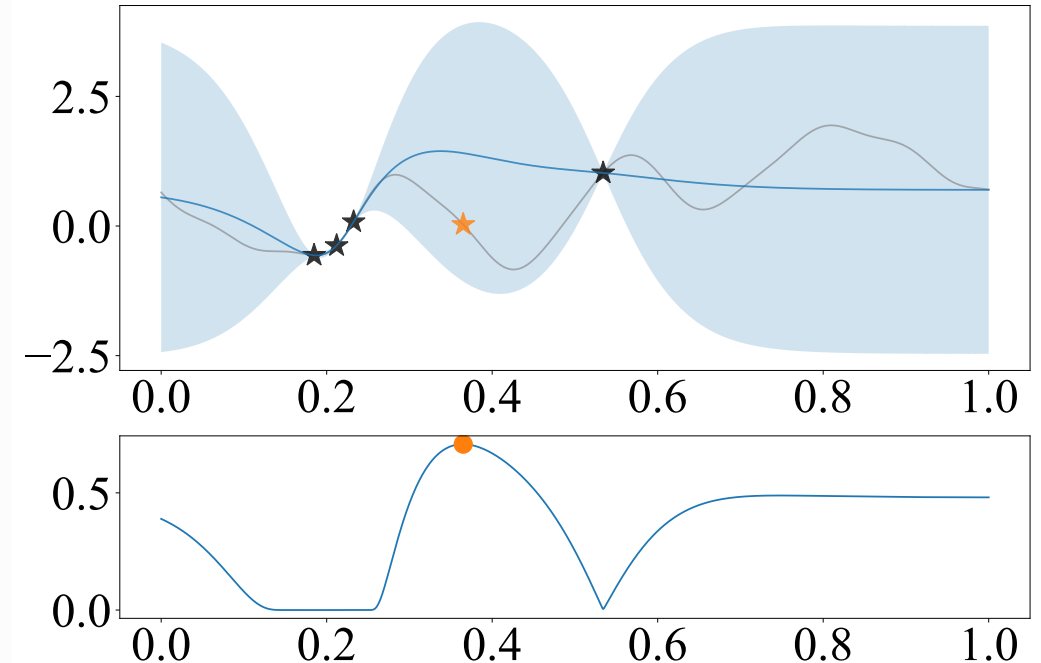
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current best observed data D

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posterior distribution

One-step approximation to MDP

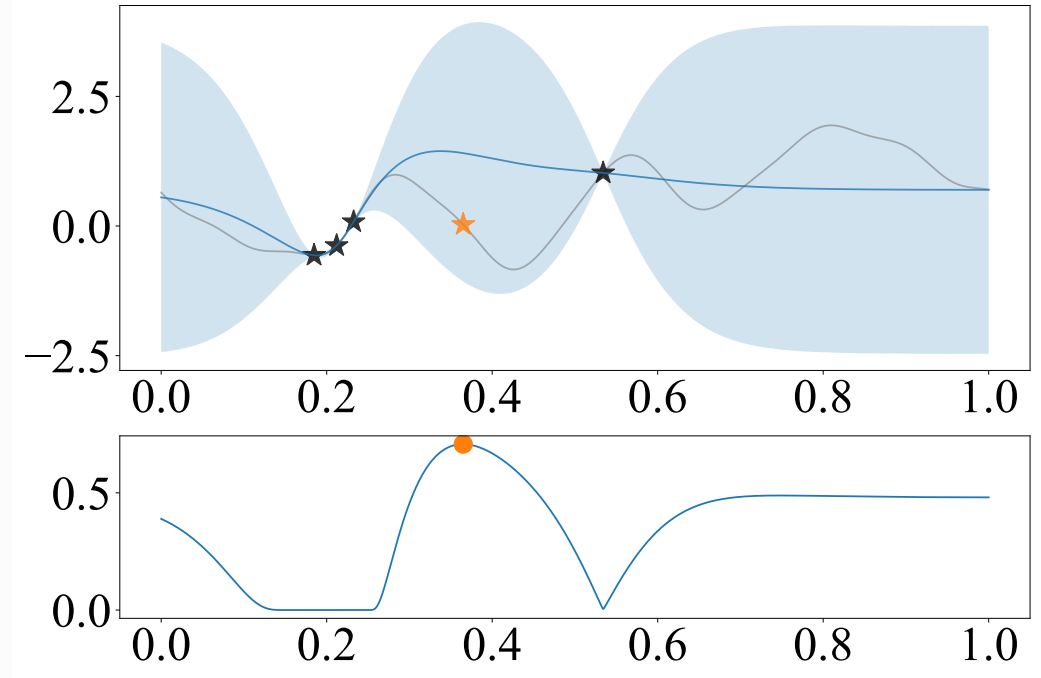


Expected improvement $\text{EI}(x)$

Improvement-based
design principle

Existing Design Principles

- Improvement-based (e.g., EI)
- Entropy-based
- Confidence bounds (UCB/LCB)
- Thompson sampling (TS)

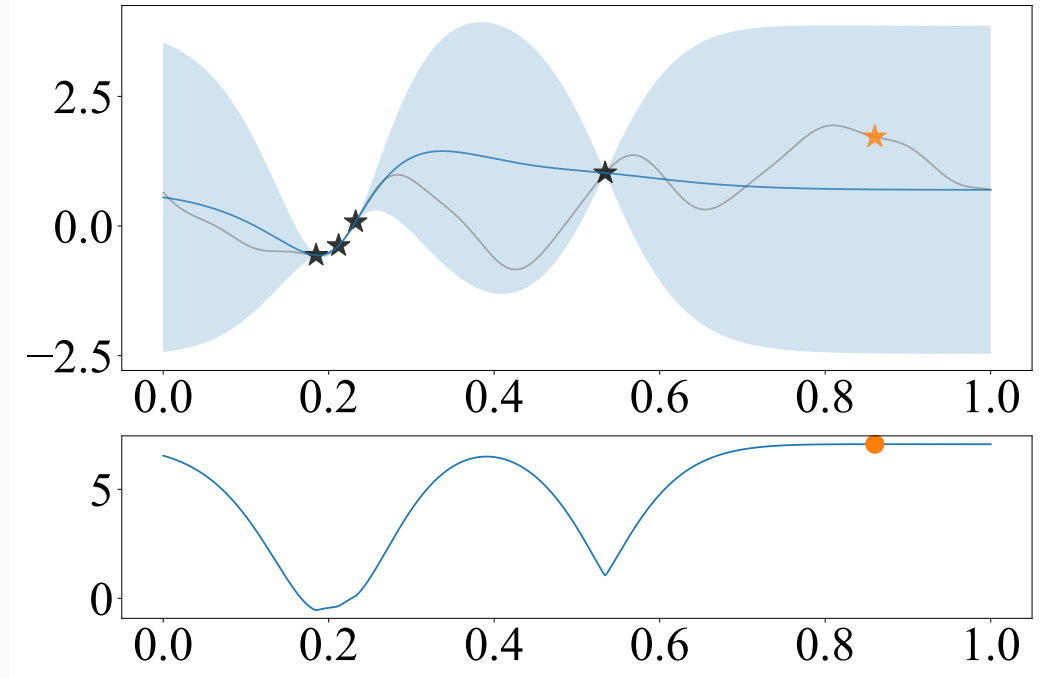


Expected improvement $EI(x)$

Improvement-based
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New Design Principle: Gittins Index

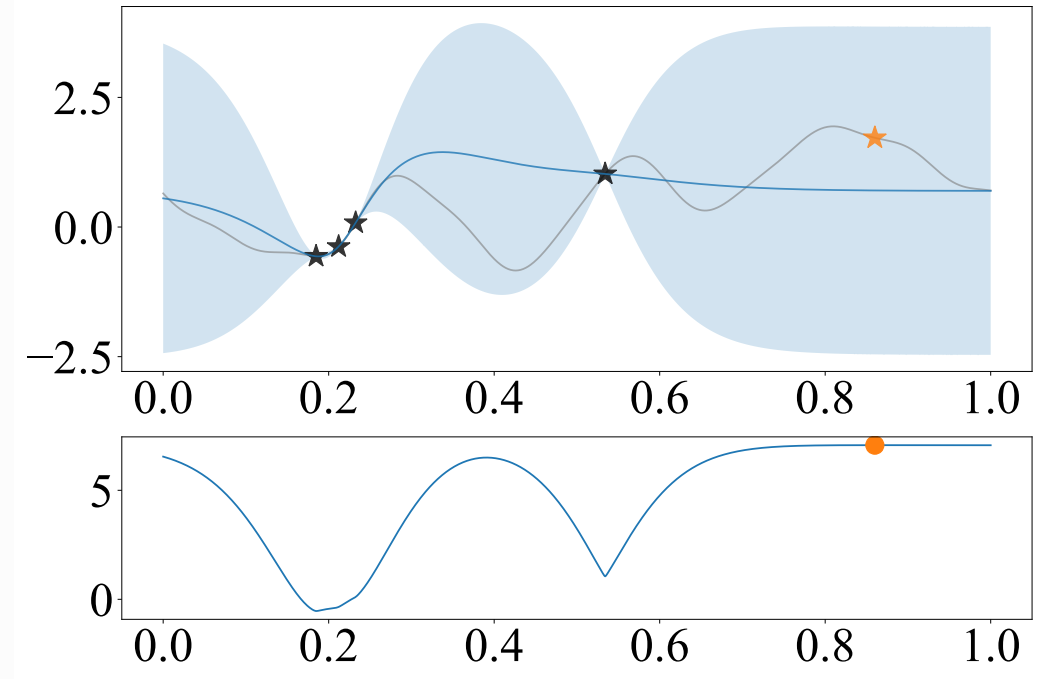
- Improvement-based (e.g., EI)
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- Confidence bounds (UCB/LCB)
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- Gittins Index



Gittins index $GI(x)$

New Design Principle: Gittins Index

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- Gittins Index



Gittins index $GI(x)$

? Why another principle?

Our Contribution: Gittins Index Principle

Joint work with Ziv Scully and Alexander Terenin et al.

1. Principled easy-to-compute decision rules
2. Natural incorporation of side info and flexibility
3. Competitive performance on benchmarks
4. Theoretical guarantees

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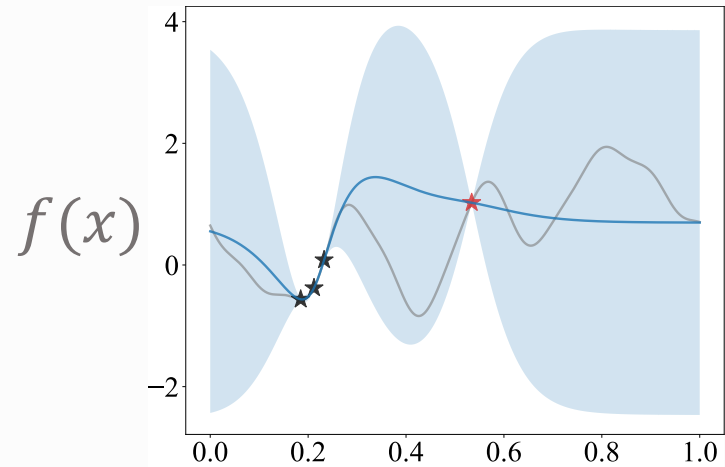
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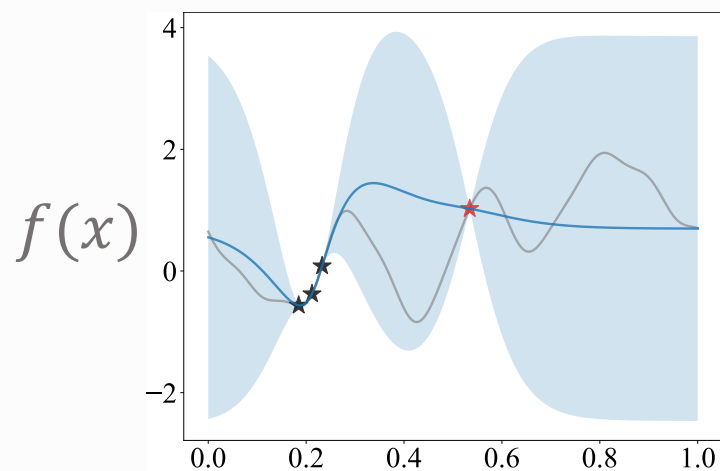
Bayesian Optimization



Continuous search space

Correlated function values

Bayesian Optimization



Continuous search space



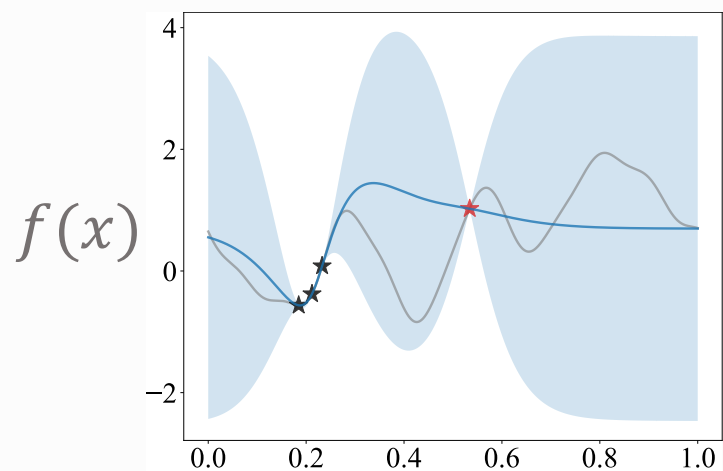
Discrete

Correlated function values



Independent

Bayesian Optimization



Continuous search space

Correlated function values

Pandora's Box

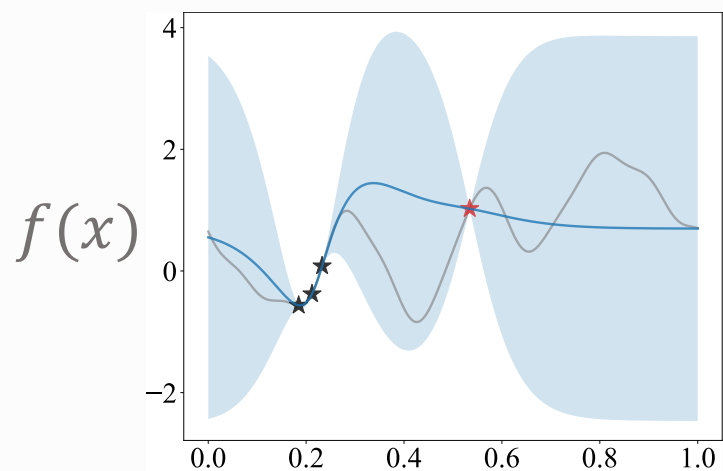
[Weitzman'79]



Discrete

Independent

Bayesian Optimization

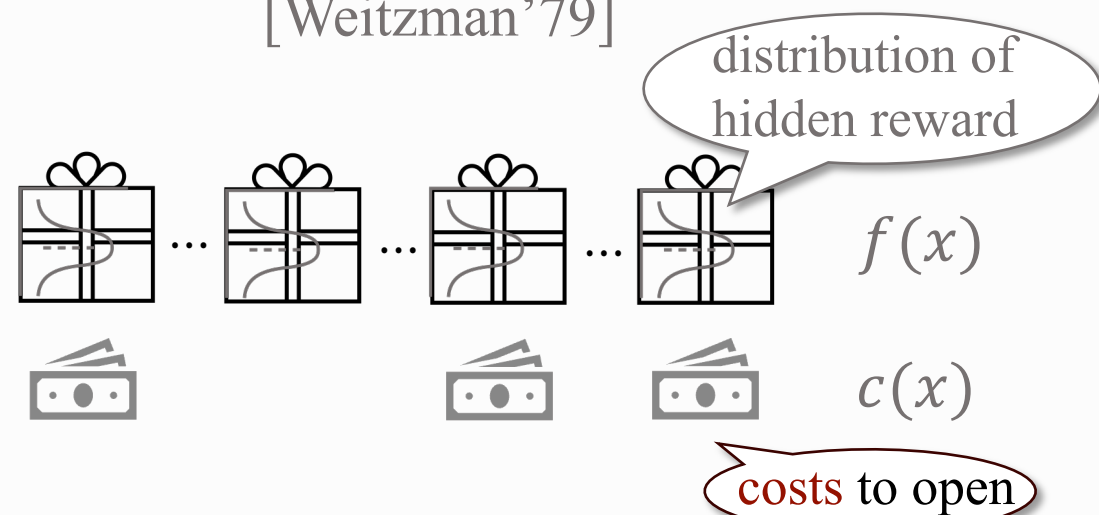


Continuous search space

Correlated function values

Pandora's Box

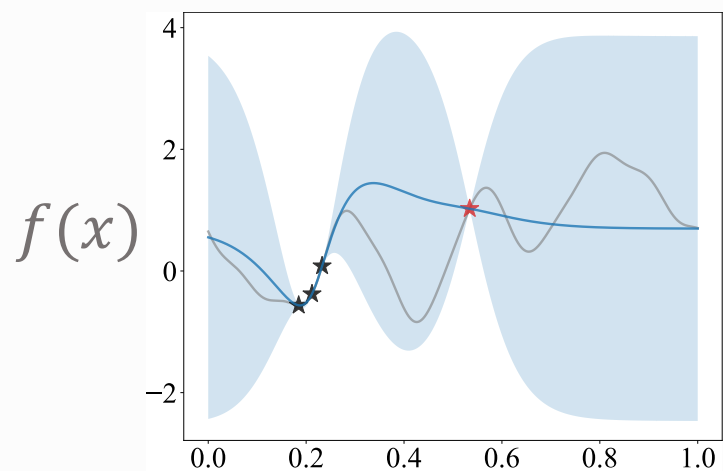
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Discrete

Independent

Bayesian Optimization

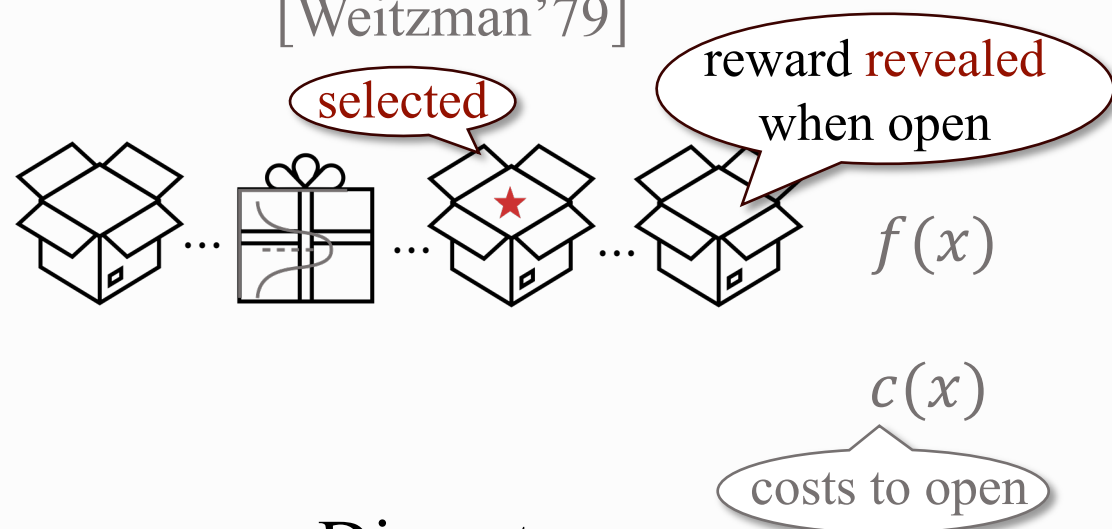


Continuous search space

Correlated function values

Pandora's Box

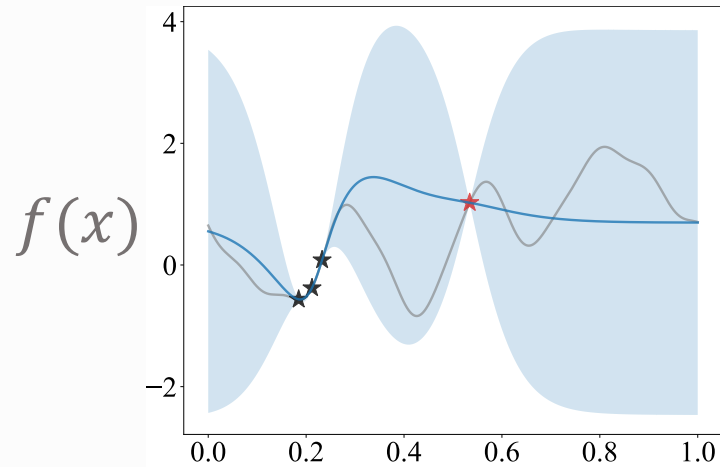
[Weitzman'79]



Discrete

Independent

Bayesian Optimization

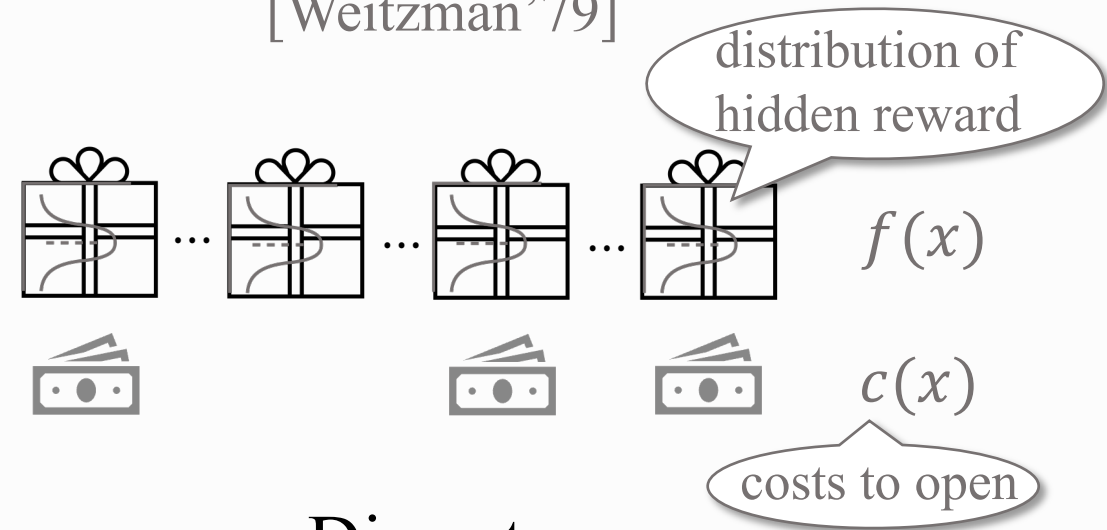


Continuous search space

Correlated function values

Pandora's Box

[Weitzman'79]

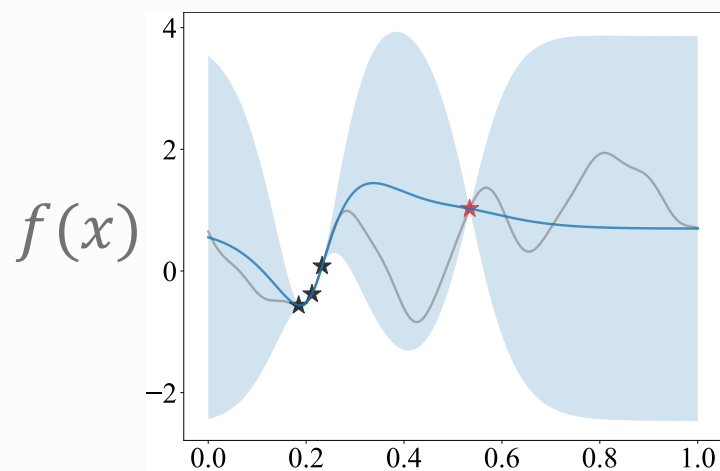


Discrete

Independent

Optimal policy: Gittins index

Bayesian Optimization

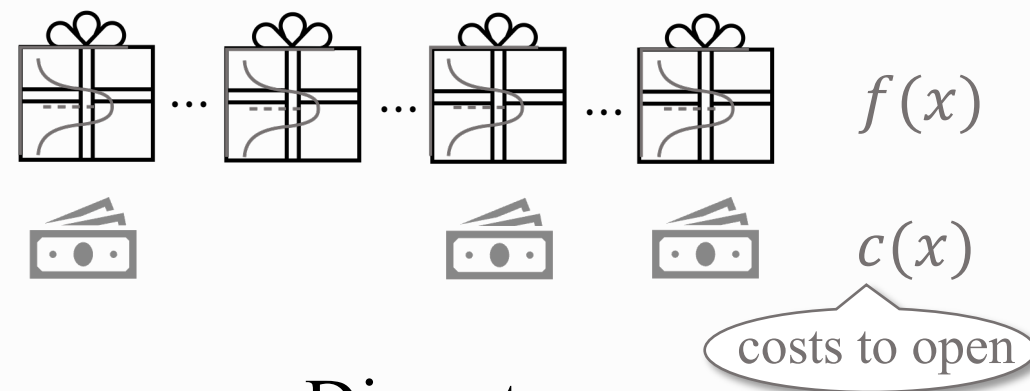


Continuous search space

Correlated function values

Pandora's Box

[Weitzman'79]



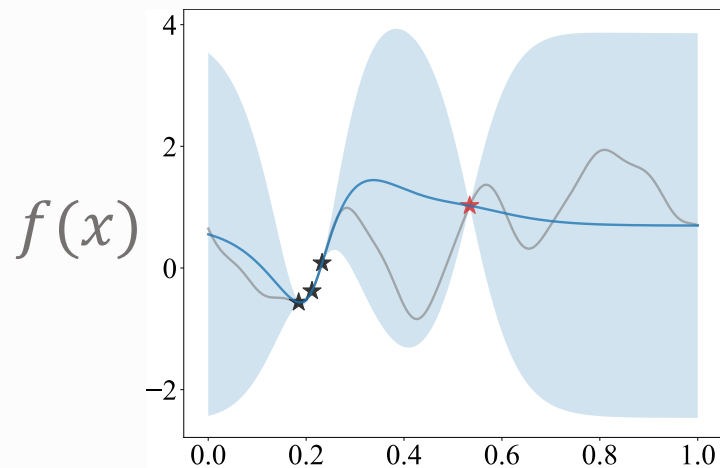
Discrete

Independent

How to translate?

⇐ Optimal policy: Gittins index

Bayesian Optimization

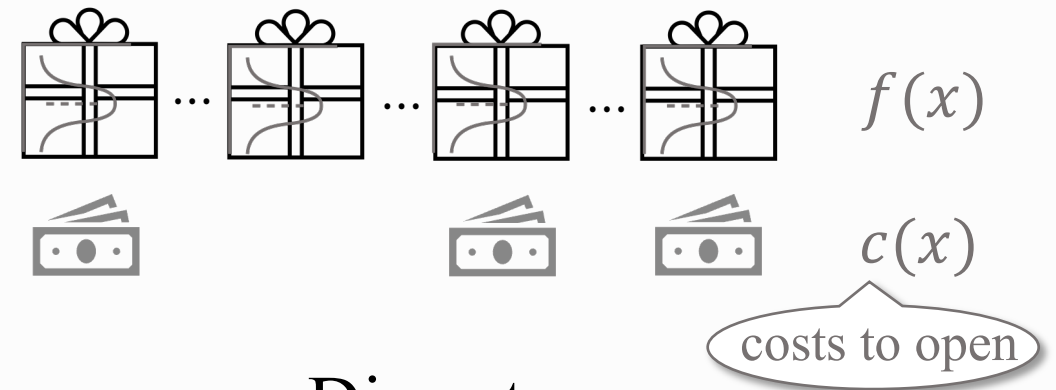


Continuous search space

Correlated function values

Pandora's Box

[Weitzman'79]



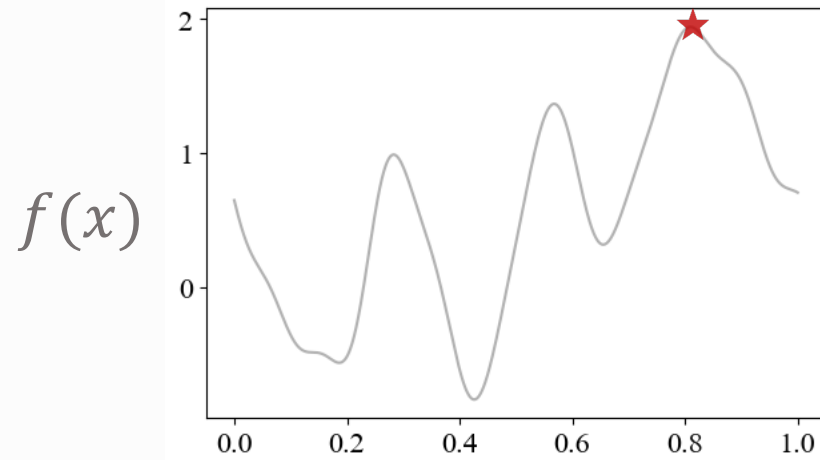
Discrete

Independent

Our policy: $\text{GI}_{f|D}(x; c)$ ← New! Optimal policy: $\text{GI}_f(x; c)$

incorporate posterior
take continuum limit

Bayesian Optimization

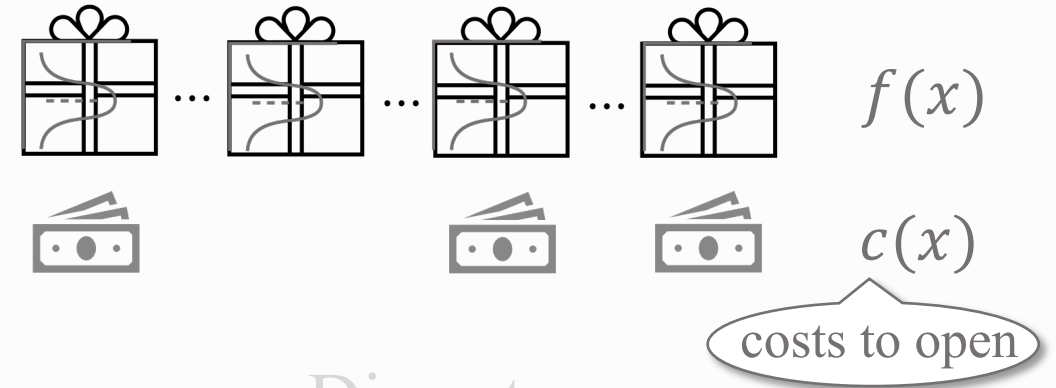


Continuous

Correlated

Pandora's Box

[Weitzman'79]



Discrete

Independent

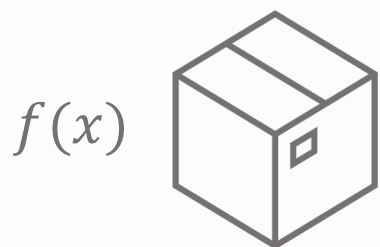
Our policy: $\text{GI}_{f|D}(x; c(x))$ $\xleftarrow[\text{take continuum limit}]{\text{incorporate posterior}}$ Optimal policy: $\text{GI}_f(x; c(x))$

How to compute?

Intuition

Exploration

Exploitation



vs.



Open closed box

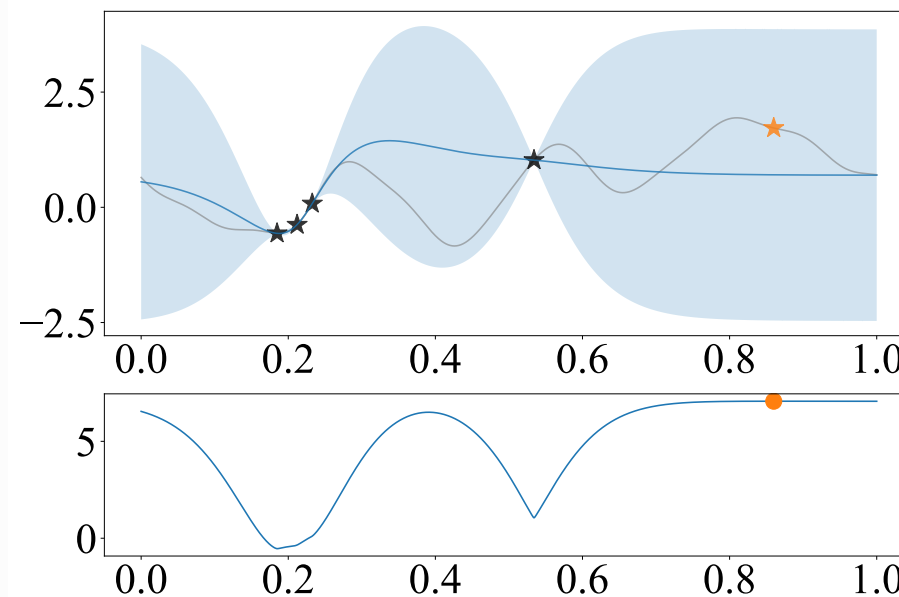
Take opened box

$$\mathbb{E}[\max(f(x), g)] - c(x)$$

g

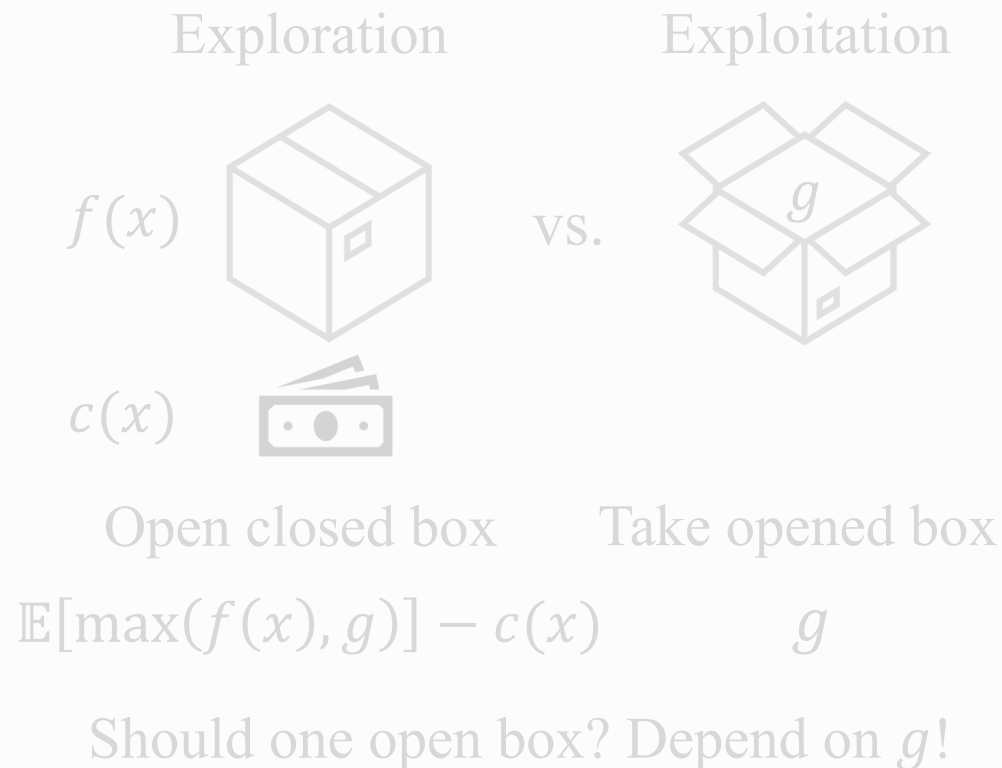
Should one open box? Depend on g !

Gittins Index

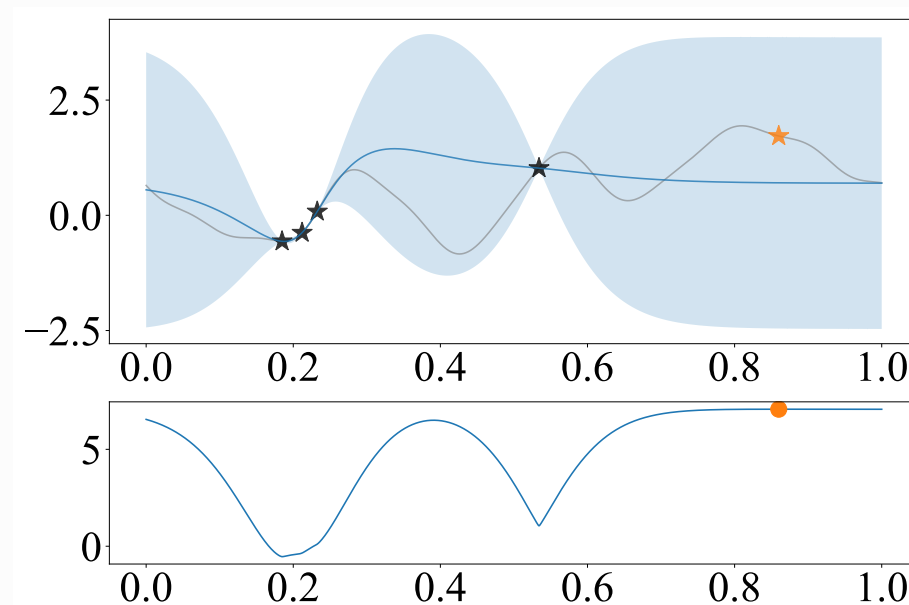


$$\text{GI}_{f|D}(x; c) := \text{solution } g \text{ s.t.} \\ \mathbb{E}[\max(f(x), g) | D] - c(x) = g$$

Intuition

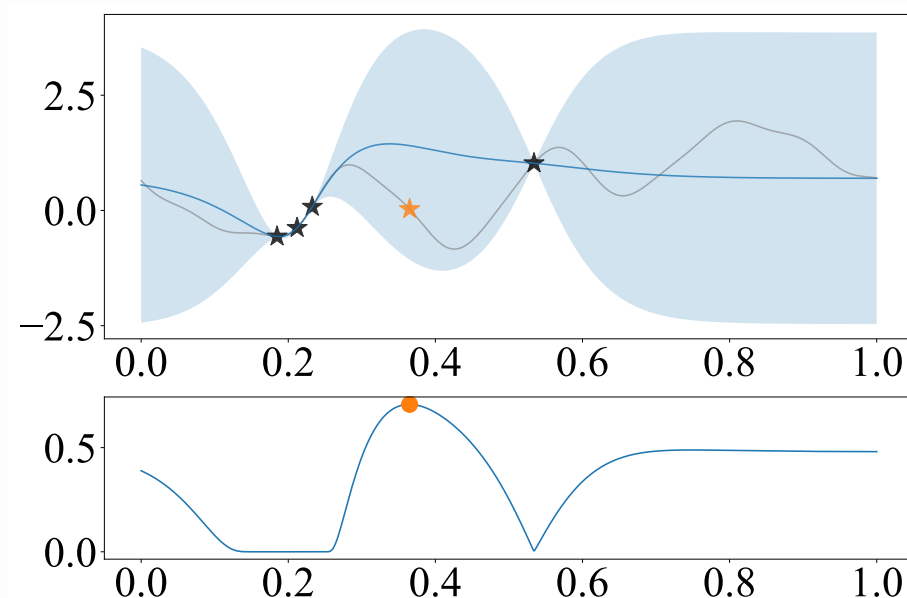


Gittins Index



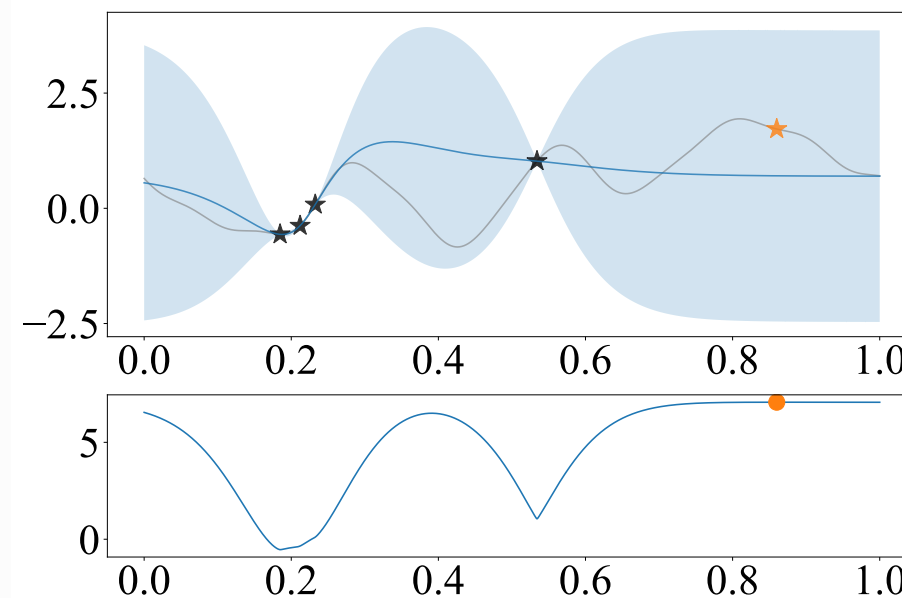
$$\begin{aligned}
 & \text{GI}_{f|D}(x; c) := \text{solution } g \text{ s.t.} \\
 & \mathbb{E}[\max(f(x), g) | D] - c(x) = g \\
 \Leftrightarrow & \mathbb{E}[\max(f(x) - g, g - g) | D] - c(x) = 0 \\
 \Leftrightarrow & \underbrace{\mathbb{E}[\max(f(x) - g, 0) | D]}_{\text{EI}_{f|D}(x; g)} = c(x)
 \end{aligned}$$

Expected Improvement



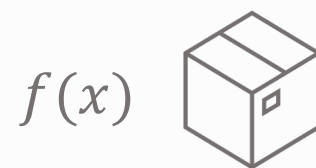
$$\text{EI}_{f|D}(x) := \mathbb{E}[\max(f(x) - y_{\text{best}}, 0) \mid D]$$

Gittins Index

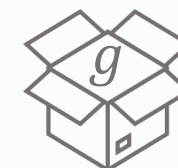


$$\text{GI}_{f|D}(x; c) := \text{solution } g \text{ s.t. } \text{EI}_{f|D}(x; g) = c(x)$$

where $\text{EI}_{f|D}(x; g) := \mathbb{E}[\max(f(x) - g, 0) \mid D]$



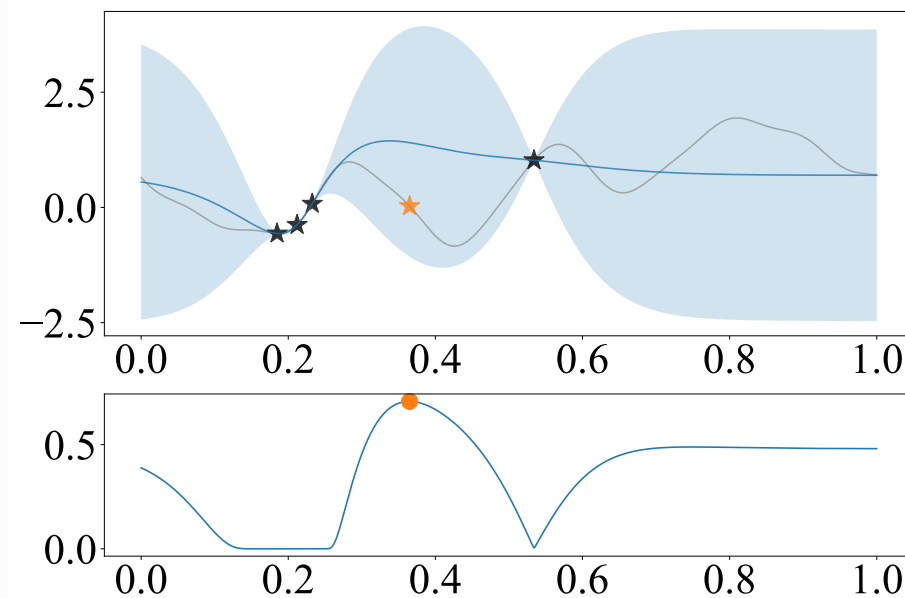
vs.



Exploration

Exploitation

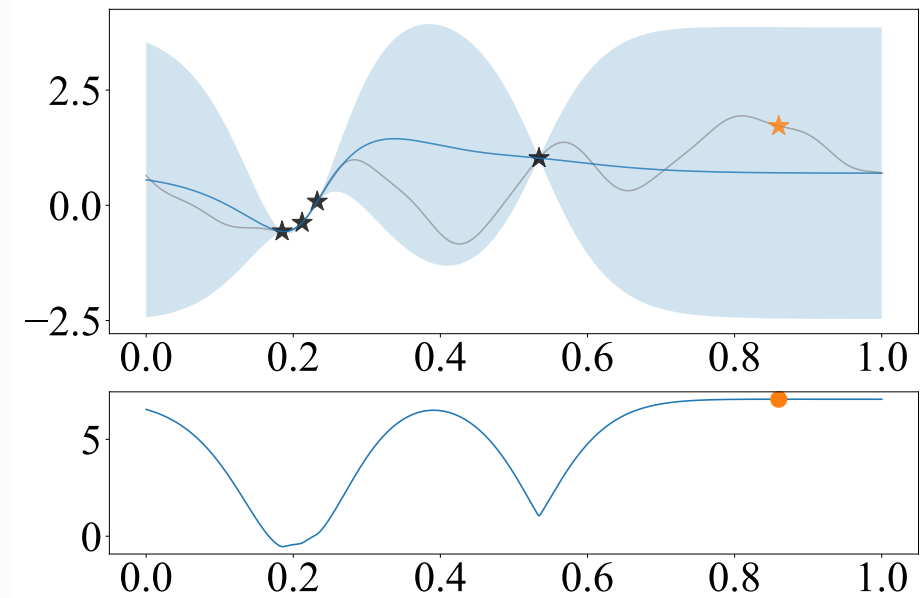
Expected Improvement



$$\text{EI}_{f|D}(x) := \mathbb{E}[\max(f(x) - y_{\text{best}}, 0) \mid D]$$

Temporal simplification to MDP
(One-step)

Gittins Index

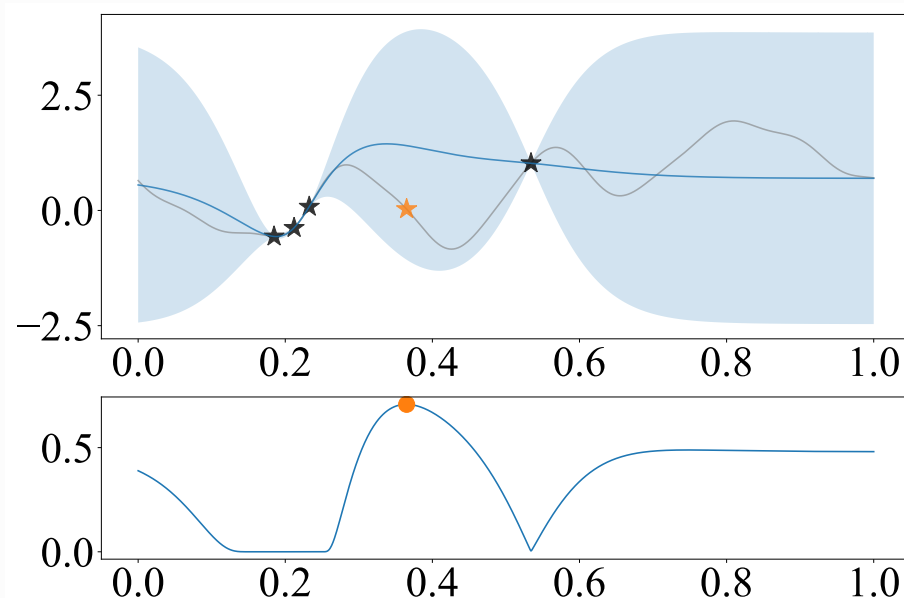


$$\text{GI}_{f|D}(x; c) := \text{solution } g \text{ s.t. } \text{EI}_{f|D}(x; g) = c(x)$$

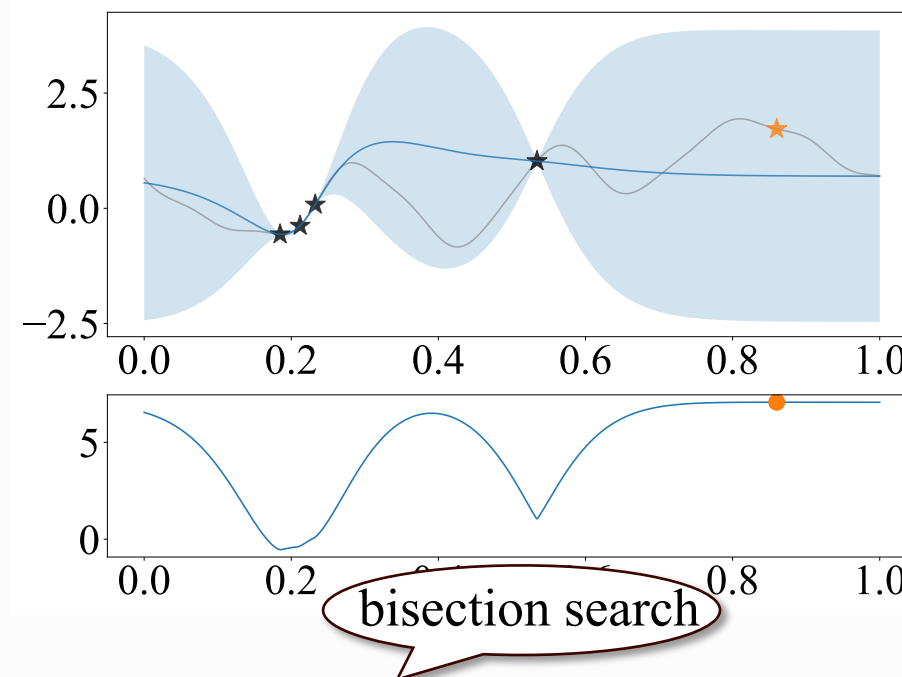
where $\text{EI}_{f|D}(x; g) := \mathbb{E}[\max(f(x) - g, 0) \mid D]$

Spatial simplification to MDP

Expected Improvement



Gittins Index



$$\text{EI}_{f|D}(x) := \mathbb{E}[\max(f(x) - y_{\text{best}}, 0) \mid D]$$

$$\text{GI}_{f|D}(x; c) := \text{solution } g \text{ s.t. } \text{EI}_{f|D}(x; g) = c(x)$$

where $\text{EI}_{f|D}(x; g) := \mathbb{E}[\max(f(x) - g, 0) \mid D]$

analytical expression

Temporal simplification to MDP

Spatial simplification to MDP

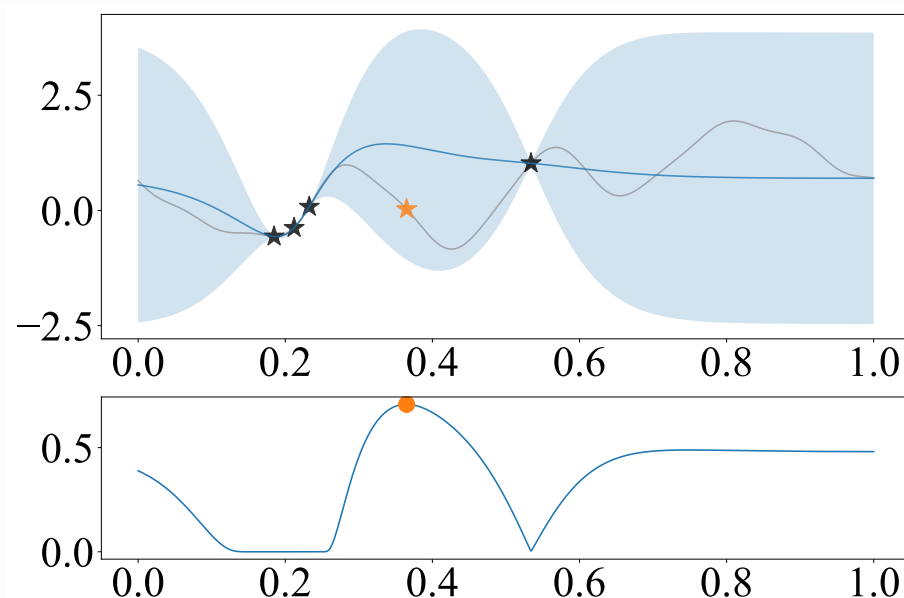


Both are **principled** and **easy-to-compute**!



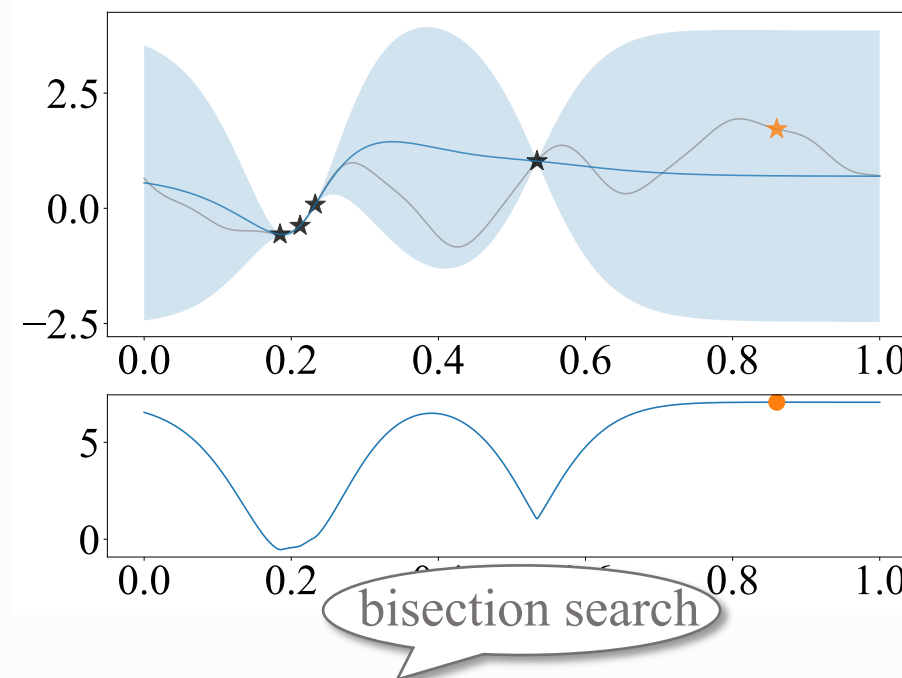
"Cost-aware Bayesian Optimization via the Pandora's Box Gittins Index." NeurIPS'24.

Expected Improvement



$$\text{EI}_{f|D}(x) := \mathbb{E}[\max(f(x) - y_{\text{best}}, 0) \mid D]$$

Gittins Index



$$\text{GI}_{f|D}(x; c) := \text{solution } g \text{ s.t. } \text{EI}_{f|D}(x; g) = c(x)$$

where $\text{EI}_{f|D}(x; g) := \mathbb{E}[\max(f(x) - g, 0) \mid D]$

Google DeepMind

FunBO: Discovering new acquisition functions for Bayesian Optimization with FunSearch

hard to discover GI

Our Contribution: Gittins Index Principle

Joint work with Ziv Scully and Alexander Terenin et al.

GI (Ours)

EI

1. Principled easy-to-compute decision rules



2. Natural incorporation of side info and flexibility



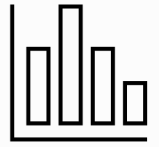
3. Competitive performance on benchmarks



4. Theoretical guarantees



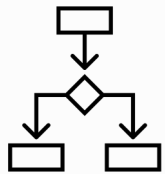
Under-explored Side Info and Practical Flexibility



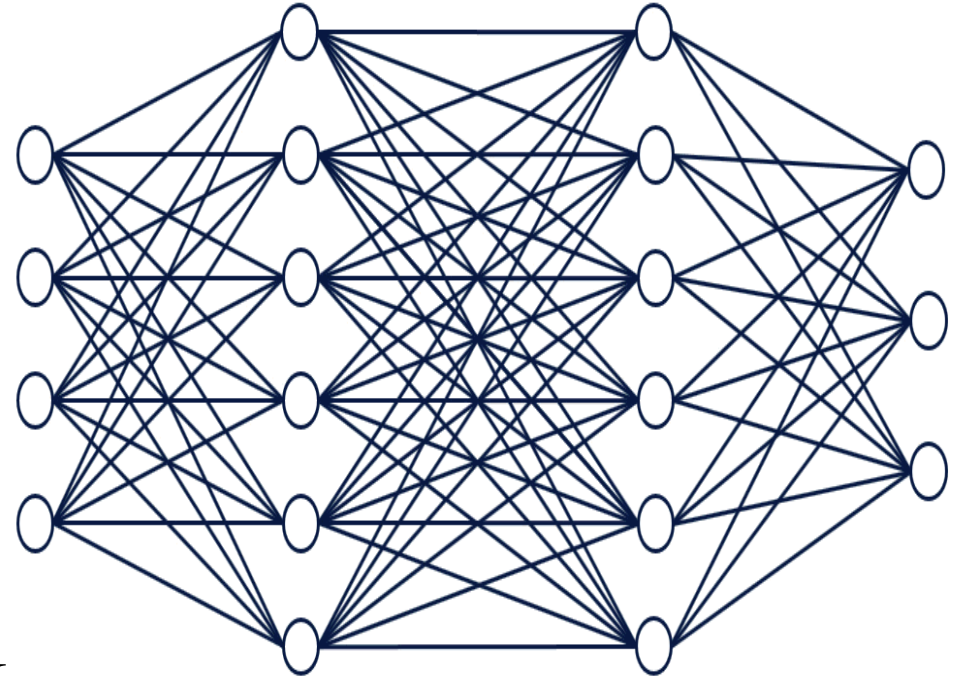
Varying evaluation costs



Smart stopping time



Observable multi-stage feedback



How does existing principle incorporate them?



Varying evaluation costs

$$\text{EIPC}(x; c) = \text{EI}(x) / c(x)$$

[Snoek et al.'12]

Arbitrarily bad

[Astudillo et al.'21]



Smart stopping time

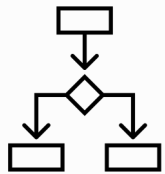
$$\tau: \text{EI}(x_\tau) \leq \theta$$

[Locatelli'97,

Nguyen et al.'17,

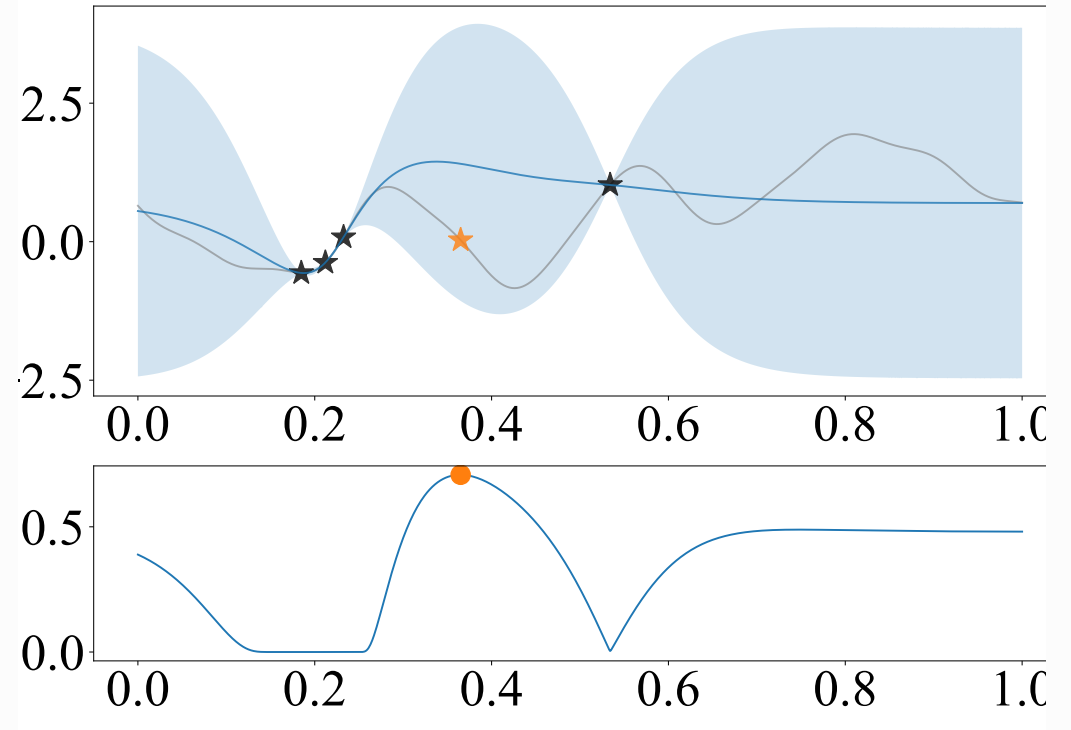
Ishibashi et al.'23]

Which threshold?



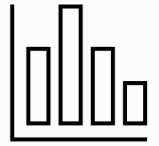
Observable multi-stage feedback

?



Expected improvement $\text{EI}(x)$

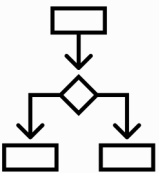
Under-explored Side Info and Practical Flexibility



Varying evaluation costs



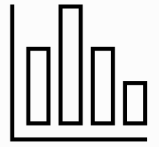
Smart stopping time



Observable multi-stage feedback

New design principle:
Gittins index

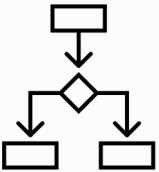
Why Gittins index?



Varying evaluation costs



Smart stopping time



Observable multi-stage feedback

New design principle:
Gittins index

Optimal in related sequential
decision problems

Why Gittins index?



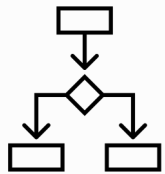
Varying evaluation costs

Features in Pandora's box



Smart stopping time

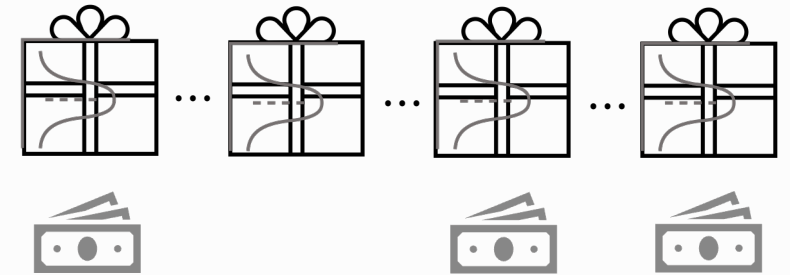
Features in Pandora's box



Observable multi-stage feedback

New design principle:
Gittins index

Optimal in related sequential
decision problems



Why Gittins index?



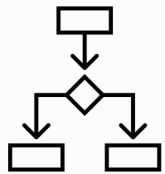
Varying evaluation costs

Features in Pandora's box



Smart stopping time

Features in Pandora's box

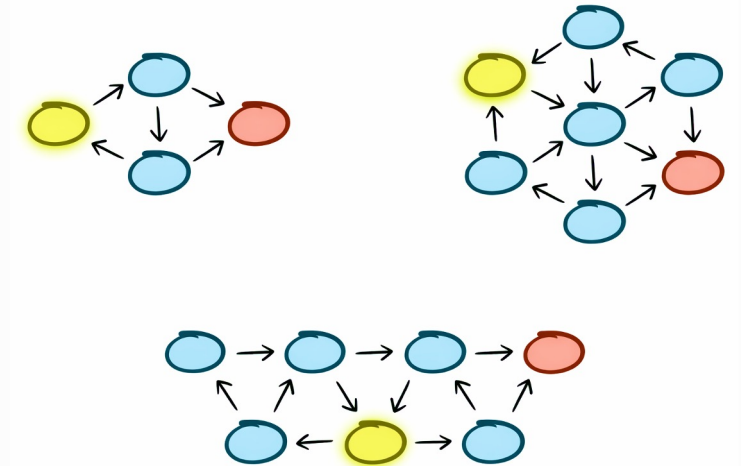


Observable multi-stage feedback

Features in **Markov chain selection**

New design principle:
Gittins index

Optimal in related sequential
decision problems



Why Gittins index?



Varying evaluation costs

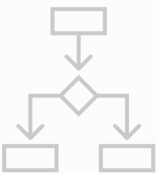
Features in Pandora's box

This talk's focus



Smart stopping time

Features in Pandora's box



Observable multi-stage feedback

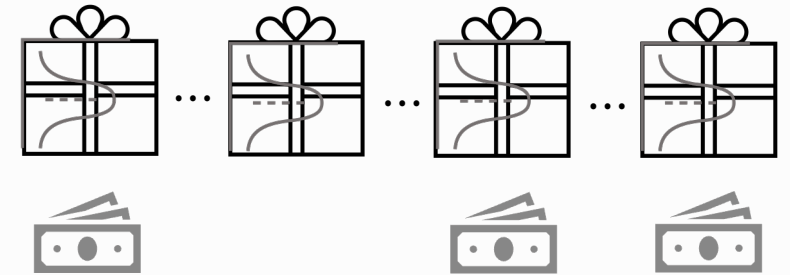
Features in Markov chain selection



"Cost-aware Bayesian Optimization via the Pandora's Box Gittins Index." NeurIPS'24.

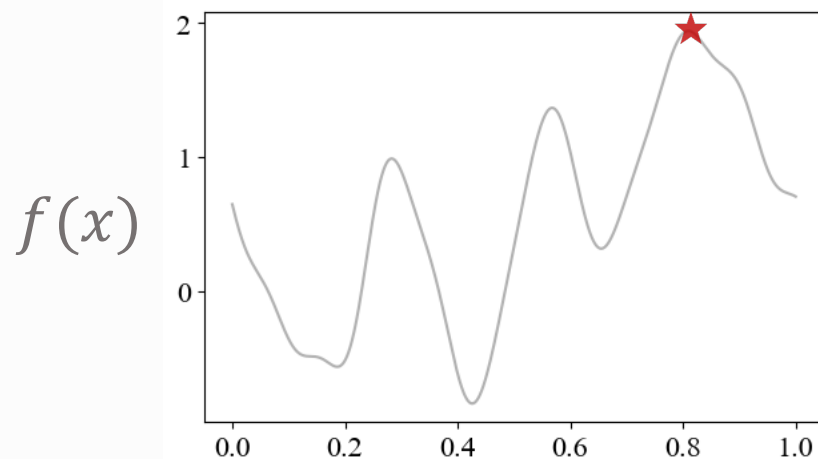
New design principle:
Gittins index

Optimal in related sequential
decision problems



"Cost-aware Stopping for Bayesian Optimization." Under review.

Bayesian Optimization



Continuous

Correlated

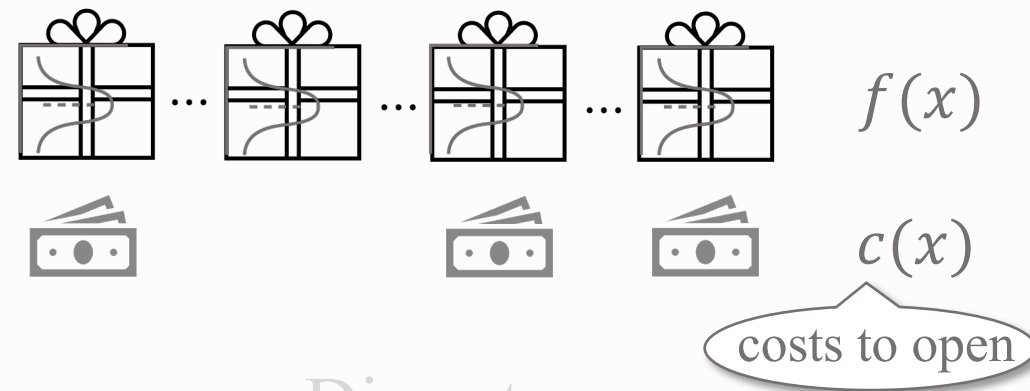
Fixed-iteration

Cost-unaware

Our policy: $\text{GI}_{f|D}(x; c)$

Pandora's Box

[Weitzman'79]



Discrete

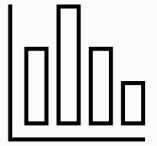
Independent

Flexible-stopping

Cost-aware

Optimal policy: $\text{GI}_f(x; c)$

Expected Improvement vs Gittins Index



Varying evaluation costs

$$\text{EIPC}(x; c) = \text{EI}(x)/c(x)$$

Arbitrarily bad

$$\text{GI}(x; c) := \text{solution } g \text{ s.t. } \text{EI}(x; g) = c(x)$$

naturally incorporates costs



Smart stopping time

$$\tau: \text{EI}(x_\tau) \leq \theta$$

Which threshold?

$$\tau: \text{GI}(x_\tau; c) \leq y_{\text{best}}$$

$$\Leftrightarrow \tau: \text{EIPC}(x_\tau; c) \leq 1$$

derived shared stopping rule



"Cost-aware Bayesian Optimization via the Pandora's Box Gittins Index." NeurIPS'24.



"Cost-aware Stopping for Bayesian Optimization." Under review.

Our Contribution: Gittins Index Principle

Joint work with Ziv Scully and Alexander Terenin et al.

GI (Ours)

EI

1. Principled easy-to-compute decision rules



2. Natural incorporation of side info and flexibility



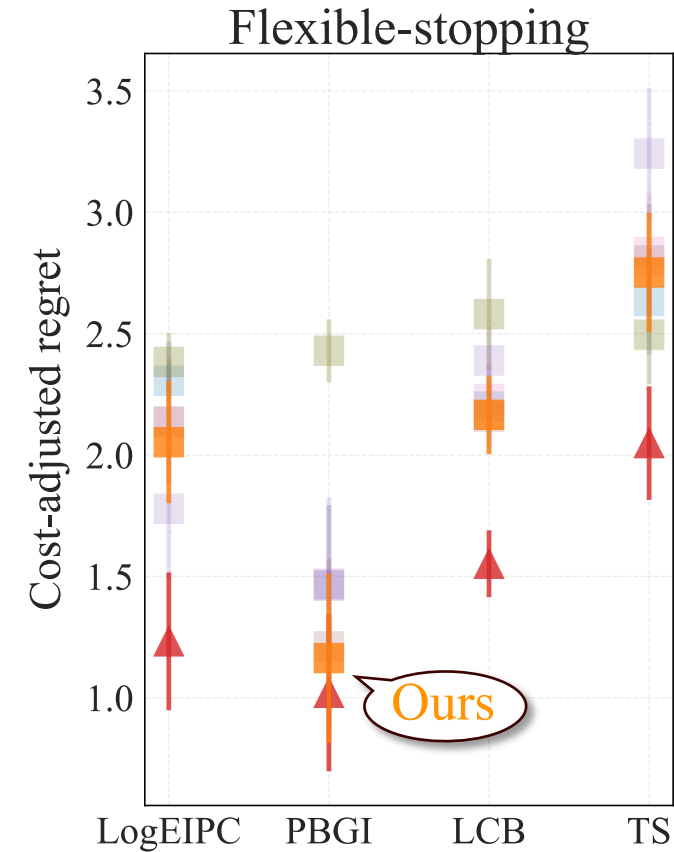
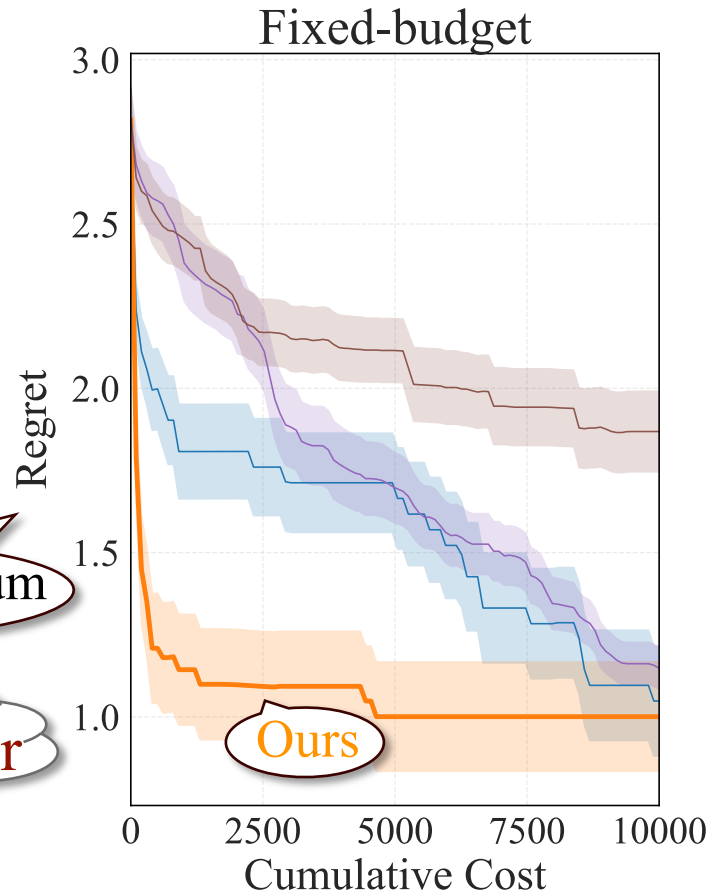
3. Competitive performance on benchmarks



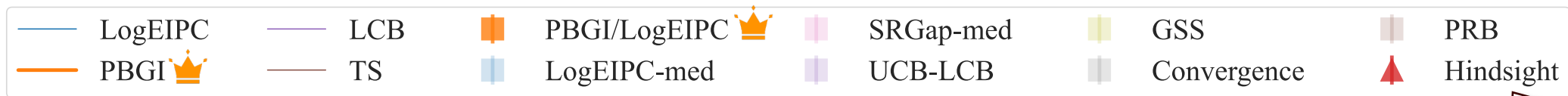
4. Theoretical guarantees



Gittins Index vs Baselines on AutoML Benchmark



Lower the better



Selection rules

Stopping rules

Not a real baseline

Our Contribution: Gittins Index Principle

Joint work with Ziv Scully and Alexander Terenin et al.

GI (Ours)

EI

1. Principled easy-to compute decision rules



2. Natural incorporation of side info and flexibility



3. Competitive performance on benchmarks



4. Theoretical guarantees



Theoretical Guarantee and Empirical Validation

Theorem (Safeguard Guarantee)

$$\mathbb{E}[R(\text{ours}; \text{PBGI})] \leq R[\text{stopping immediately}]$$

or LogEIPC cost-adjusted regret

Implication:

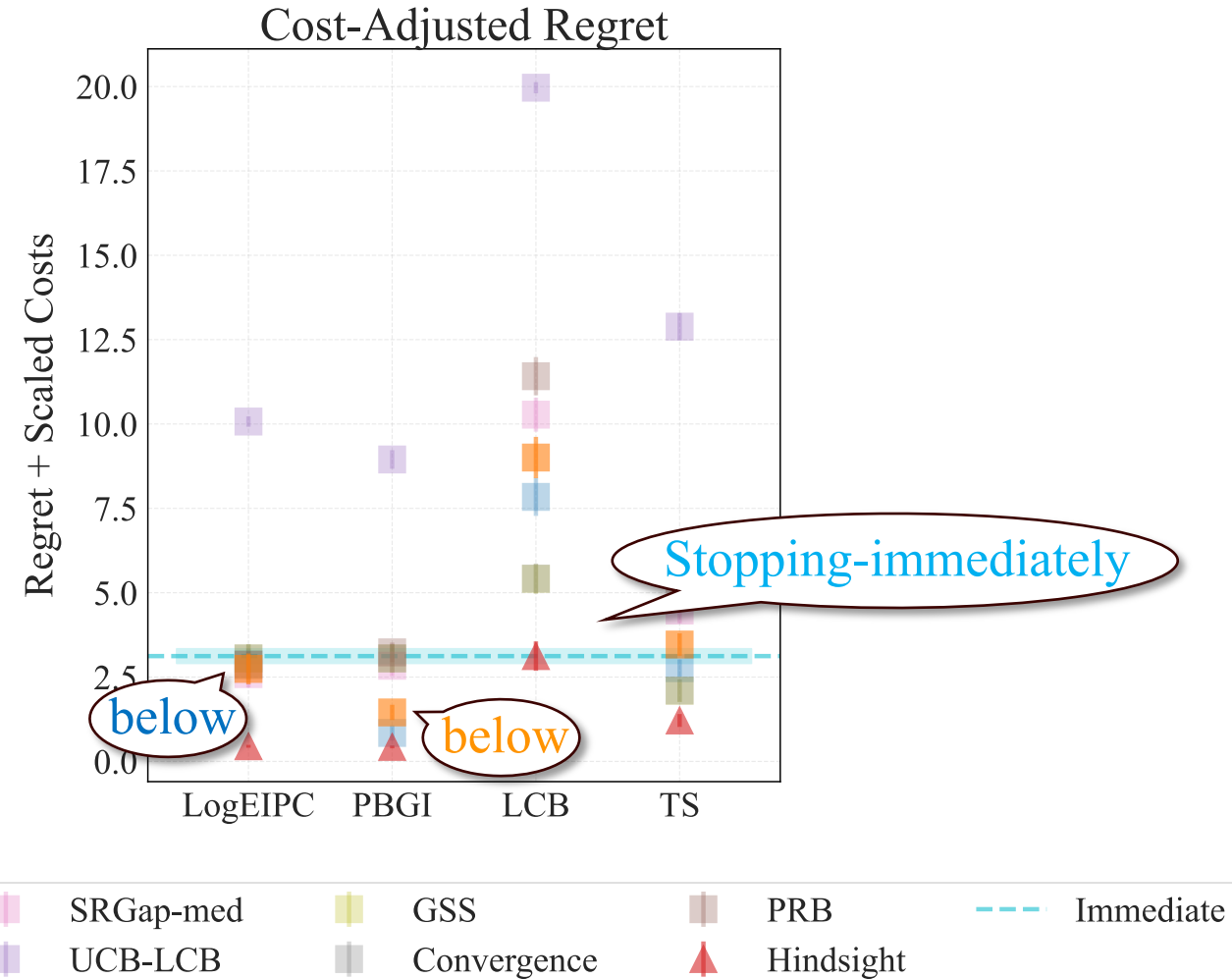
- Matches the **best achievable performance in the worst case** (evaluations are all very costly).

- Avoids over-spending** — a property many cost-unaware stopping rules lack.

New

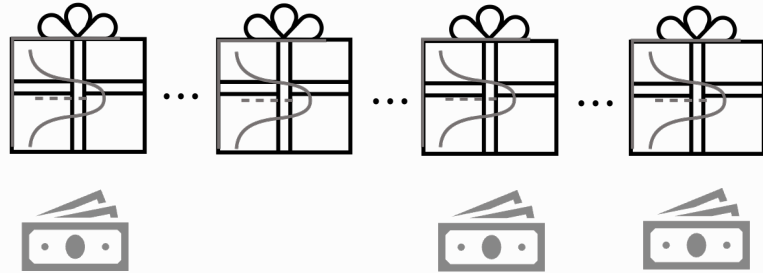
Proof idea: For all $t < \tau$, $\text{EI}(x_{t+1}) \geq c(x_{t+1})$.

stopping time



"Cost-aware Stopping for Bayesian Optimization." Under review.

Principled decision rules

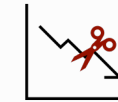


Link to **Pandora's Box** problem
& **Gittins index** theory

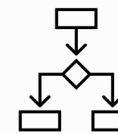
Natural incorporation of side info



Varying evaluation costs

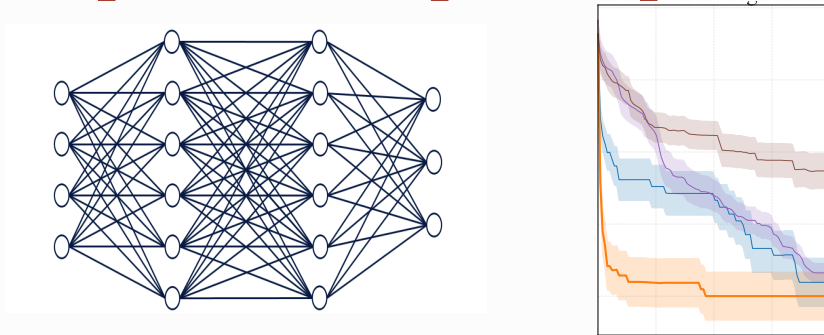


Adaptive stopping time



Multi-stage feedback

Competitive empirical performance



Interests from practitioners (e.g., Meta)



"Cost-aware Bayesian Optimization via the Pandora's Box Gittins Index." NeurIPS'24.

Theoretical guarantees

$$\mathbb{E}[R(\text{ours}; \text{PBGI})] \leq R[\text{stopping immediately}]$$

Ongoing: regret bound

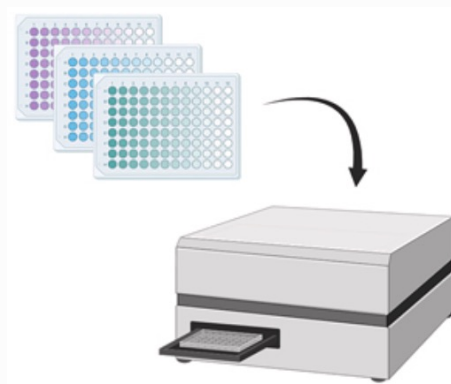
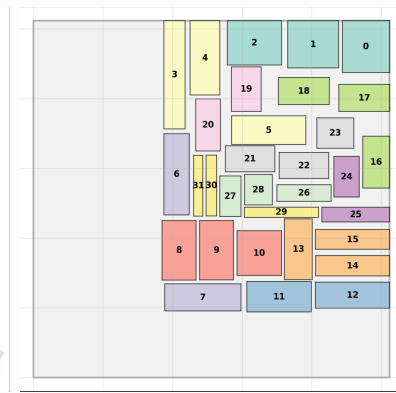
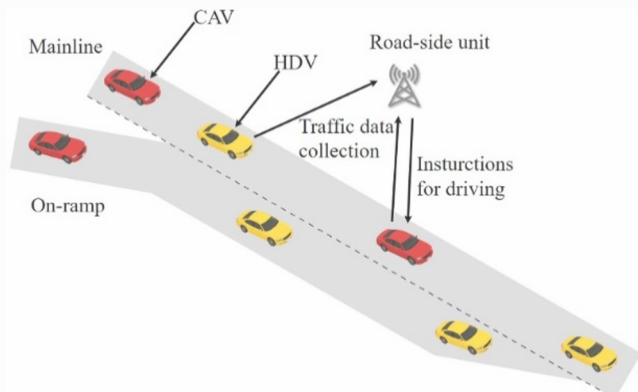


"Cost-aware Stopping for Bayesian Optimization." Under review.

Part II (Ongoing):

Black-box Optimization Beyond AutoML

Reinforcement Learning · Engineering Design · Scientific Discovery · Emerging AI Systems (LLM)



| | Zero-shot | Few-shot | CoT | RAG | Revise |
|-------------------|-----------|----------|-------|-------|--------|
| ChatGPT (GPT-4.1) | ★★★★★ | ★★★★★ | ★★★★★ | ★★★★★ | ★★★★★ |
| Claude 3.5 Sonnet | ★★★★★ | ★★★★★ | ★★★★★ | | ★★★★★ |
| Gemini 1.5 Pro | ★★★★★ | ★★★ | ? | ★★★★ | ★★★★★ |
| deepseek | ? | ? | ★★★★ | ? | ★★★★ |
| Llama 3.1-70B | ? | ? | ★★★★ | ? | ★★★ |
| Mistral Large | ? | ? | ★★★ | ? | ★ |